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Hirasugar Institute of Technology, Nidasoshi.

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Inculcating Values, Promoting Prosperity

ECE Dept.

Exam.

Internal Assessment

Odd Sem(2018-19)

**FIRST INTERNAL ASSESSMENT**

Sem: VII

Date: 12/09/2018

Sub: Satellite Communication

Time: 11am -12 noon

Sub. Code:15EC755

Max. Marks:25

*Note: Answer two full questions, draw sketches wherever necessary.*

Q. No	Description of Question	Marks	CO	RBT LEVEL
1	a Explain Kepler laws of planetary motion with neat sketch and equations.	7	C405a.1	L2
	b Define the following. i) Apogee ii) Inclination iii) Prograde orbit iv) Ascending Node v) Argument of Perigee vi) Eccentricity	6	C405a.1	L2
<b>OR</b>				
2	a The elliptical eccentric orbit of a satellite has its semi-major and semi-minor axes as 25000 km and 18330 km respectively. Determine the apogee and perigee distances.	7	C405a.1	L2
	b Define the following i) Orbit ii) Trajectory ii) Sun Synchronous Orbit iv) Newton's 2 <sup>nd</sup> law of motion v) Elevation angle vi) Station Keeping	6	C405a.1	L3
3	a Explain spin and three axis stabilization of satellite orbit.	6	C405a.1	L3
	b Explain the types of satellite orbits.	6	C405a.1	L2
<b>OR</b>				
4	a A satellite in the Intelsat-VI series is located at 37°W and another belonging to the Intelsat-VII series is located at 74°E (Figure 3.37). If both these satellites are in a circular equatorial geostationary orbit with an orbital radius of 42164 km, determine the intersatellite distance.	6	C405a.1	L3
	b Write a note on injection velocity.	6	C405a.1	L2

  
Course Coordinator

(Prof. S B Akkole)

  
Module Coordinator



(Prof. S B Akkole)

  
HOD

(Dr. V G Kasabegoudar)



IA - I SCHEME OF EVALUATION

Sem : (VII)	Subject : Satellite Communication	Sub Code : 15EC75	Date : 12/9/2018
Q. No.	Bit	Description	Marks
1	(a)	<p>Each law with sketches <del>2+2+2</del> 2.5+2.5+2</p> <p>(i) Path followed by a sat around the earth is ellipse</p>  <p>(ii) Sat covers same area in in same equal orbits equally</p> $\frac{dA}{dt} = \frac{\text{angular momentum of sat}}{2m}$ <p>m - mass of sat</p>  <p>(iii) The square of time period of any satellite is proportional to the cube of semimajor axis in elliptical orbit</p> $T^2 \propto a^3 \text{ or } T = \frac{2\pi}{\sqrt{\mu}} a^{3/2}$	7
	(b)	<p>Defining each parameter</p> <p>1+1+1+1+1+1=6</p> <p>a = 25000 km    b = 18330 km</p> $e = \frac{\sqrt{a^2 - b^2}}{a} = \frac{\sqrt{(25000)^2 - (18330)^2}}{25000}$ <p>= 0.68 (2M)</p> $A = a(1+e) = 25000(1+0.68)$ <p>= 42000 km (2M)</p>	6M.
2	(a)	<p>Defining each parameter</p> <p>1+1+1+1+1+1=6</p> <p>a = 25000 km    b = 18330 km</p> $e = \frac{\sqrt{a^2 - b^2}}{a} = \frac{\sqrt{(25000)^2 - (18330)^2}}{25000}$ <p>= 0.68 (2M)</p> $A = a(1+e) = 25000(1+0.68)$ <p>= 42000 km (2M)</p>	6M

CO's	RBT LEVEL
CUOSA-1	L2

CUOSA-1	L2
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CUOSA-1	L3
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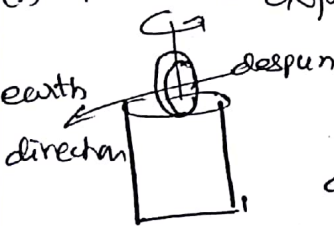
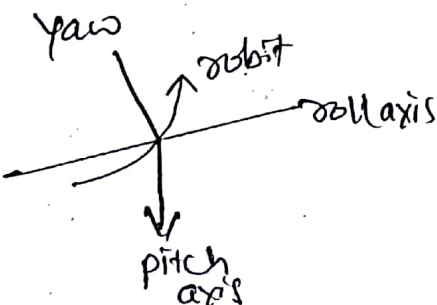
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IA - I SCHEME OF EVALUATION

Sem : VII		Subject : Satellite Communication	15EC751	Date : 12/9/2018		
Q. No.	Bit	Description	Sub Code :	Marks	CO's	RBT LEVEL
2	(a)	$P = a(1-e) = 25000(0.32)$ $= 8000 \text{ km}$ <p style="text-align: right;">(2m)</p>				
2	(b)	Defining each 1 marks each $1+1+1+1+1 = 5$		6M	CO's-1	L2
3	(a)	(i) Spin axis explanation & M+1 figure  <p style="text-align: right;">Body spins @ 30 to 100 rpm axis ⊥ to orbit plane</p> <p style="text-align: right;">It maintains the moment of inertia maximum &amp; wt. greater than the spin axis — 3m.</p> (ii) Three axis stabilization.  <p style="text-align: right;">Is achieved by controlling 3 axis yaw, roll &amp; pitch axis. The reaction momentum wheels are used. The wheels are speed up or slow down according to satellite direction.</p> <p style="text-align: right;">In reaction wheel, reaction force is generated which opposite the</p>		6	CO's-1	L2

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**IA - I SCHEME OF EVALUATION**

Sem : VII	Subject : <u>Satellite Comm</u>	Sub Code : <u>ISEC755</u>	Date : <u>12/9/2018</u>	Marks	CO's	RBT LEVEL
Q. No.	Bit	Description				
3	(b)	<p>Satellite in undesired orbit &amp; allow to move in desired orbit. eg. INSATS.</p> <p>Explaining any 6 orbits of the satellite +++++</p> <p>(i) orientation of the orbital plane - equatorial orbit, polar orbit prograde orbit &amp; retrograde orbit</p> <p>(ii) orbit types - Eccentricity: elliptical &amp; circular</p> <p>(iii) Distance from the earth - LEO, MEO &amp; GEO</p>		6M.	CUOSA-1	L2
4	(a)	<p><math>\theta = 37 + 74 = 111^\circ</math> — (1)</p> <p><math>D_1 = 42164 \text{ km}</math> ; <math>D_2 = 42164 \text{ km}</math></p> <p>∴ Intersat distance <math>D = \sqrt{D_1^2 + D_2^2 - 2 D_1 D_2 \cos \theta}</math> — (1)</p> <p style="margin-left: 40px;"><math>= \sqrt{(42164)^2 + (42164)^2 - 2 (42164)^2 \cos 111^\circ}</math></p> <p style="margin-left: 40px;"><math>D = 69086.27 \text{ km}</math> — (2)</p>		6M	CUOSA-1	L3
	(b)	<p>The horizontal velocity with which a sat is injected into space by the launch vehicle with intention of imparting a specific trajectory to the sat has a direct bearing on the sat trajectory</p> <p style="margin-left: 40px;"><math>v_p = \sqrt{\frac{2M}{P} - \frac{2M}{A+P}}</math> at perigee <math>A=P</math></p> <p style="margin-left: 40px;"><math>v_i = v_p = \sqrt{\frac{M}{P}}</math></p>		6M.	CUOSA-1	L2

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IA - 2 SCHEME OF EVALUATION

Sem : VI		Subject : Satellite Comm	ISECT55	Date : 12/9/2018		
Q. No.	Bit	Description	Sub Code :	Marks	CO's	RBT LEVEL
		<p>If <math>v_p</math> greater than 1st cosmic velocity then</p> $v_p = \sqrt{\frac{2M}{P} - \frac{2M}{A+P}} = \frac{v_d \cos \nu}{P}$ <p>When the injection velocity equals <math>\sqrt{2M/P}</math> the apogee distance <math>A</math> becomes infinite &amp; the orbit takes the shape of parabola &amp; <math>e=1</math> This is second cosmic velocity <math>v_2</math>.</p> <p>If the injection velocity increased further the sat succeed in escaping the solar system. This is known as Third cosmic velocity</p>				

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