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Department of Electronics & Communication Engg.

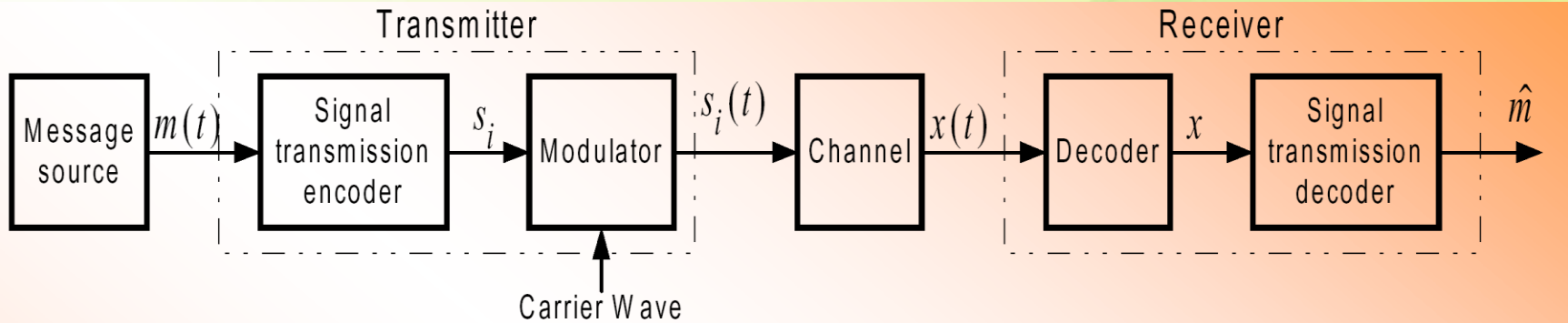
Course : Digital Communication -15EC61.

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Course Coordinator:

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Band pass Modulation and Demodulation



- Bandpass Modulation is the process by which some characteristics of a sinusoidal waveform is varied according to the message signal.
- **Modulation** shifts the spectrum of a baseband signal to some high frequency.
- Demodulator/Decoder baseband waveform recovery

Why Modulate?

- Most channels require that the baseband signal be shifted to a higher frequency
- For example in case of a wireless channel antenna size is inversely proportional to the center frequency, this is difficult to realize for baseband signals.
 - For speech signal $f = 3 \text{ kHz} \Rightarrow \lambda = c/f = (3 \times 10^8)/(3 \times 10^3)$
 - Antenna size without modulation $\lambda/4 = 10^5/4 \text{ meters} = 15 \text{ miles}$ - **practically unrealizable**
 - Same speech signal if amplitude modulated using $f_c = 900 \text{ MHz}$ will require an antenna size of about 8cm.
 - This is evident that efficient antenna of realistic physical size is needed for radio communication system
- Modulation also required if channel has to be shared by several transmitters (Frequency division multiplexing).

Digital Band pass Modulation Techniques

Three ways of representing bandpass signal:

- (1) Magnitude and Phase (M & P)

- Any bandpass signal can be represented as:

$$s(t) = A(t) \cos[\theta(t)] = A(t) \cos[\omega_0 t + \phi(t)]$$

- $A(t) \geq 0$ is real valued signal representing the magnitude
 - $\Theta(t)$ is the generalized angle
 - $\phi(t)$ is the phase
- The representation is easy to interpret physically, but often is not mathematically convenient
 - In this form, the modulated signal can represent information through changing three parameters of the signal namely:
 - Amplitude $A(t)$: as in Amplitude Shift Keying (**ASK**)
 - Phase $\phi(t)$: as in Phase Shift Keying (**PSK**)
 - Frequency $d\Theta(t)/dt$: as in Frequency Shift Keying (**FSK**)

Angle Modulation

- Consider a signal with constant frequency:

$$s(t) = A(t) \cos(\theta(t)) = A(t) \cos(\omega_0 t + \varphi)$$

- Its instantaneous frequency can be written as:

$$\omega_i(t) = \frac{d\theta(t)}{dt} = \omega_0$$

or

$$\theta(t) = \int_{-\infty}^t \omega_i(\alpha) d\alpha$$

Phase Shift Keying (PSK) or PM

- Consider a message signal $m(t)$, we can write the phase modulated signal as

$$\theta(t) = \omega_c t + K_p m(t)$$

$$s_{PM}(t) = A \cos[\omega_c t + K_p m(t)]$$

$$\omega_i(t) = \frac{d\theta}{dt} = \omega_c + K_p m'(t)$$

Frequency Shift Keying (FSK) or FM

- In case of Frequency Modulation

$$\omega_i(t) = \omega_0 + K_f m(t)$$

$$\theta(t) = \int_{-\infty}^t [\omega_0 + K_f m(\alpha)] d\alpha$$

$$= \omega_0 t + K_f \int_{-\infty}^t m(\alpha) d\alpha$$

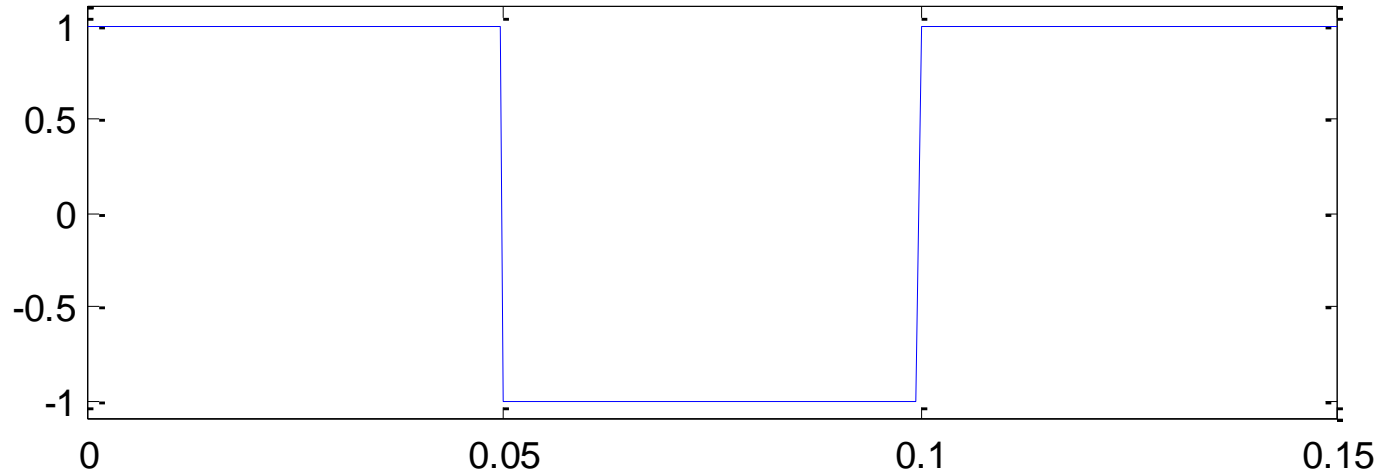
$$s_{FM}(t) = A \cos[\omega_0 t + K_f \int_{-\infty}^t m(\alpha) d\alpha]$$
$$= A \cos[\omega_0 t + K_f a(t)]$$

where:

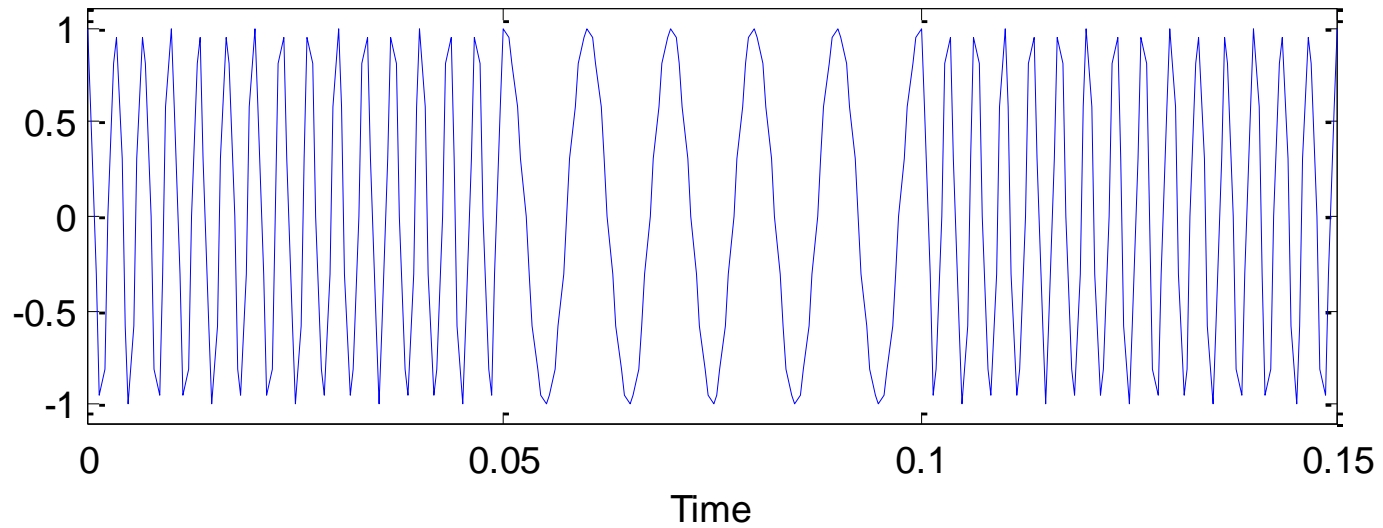
$$a(t) = \int_{-\infty}^t m(\alpha) d\alpha$$

Example

The message signal



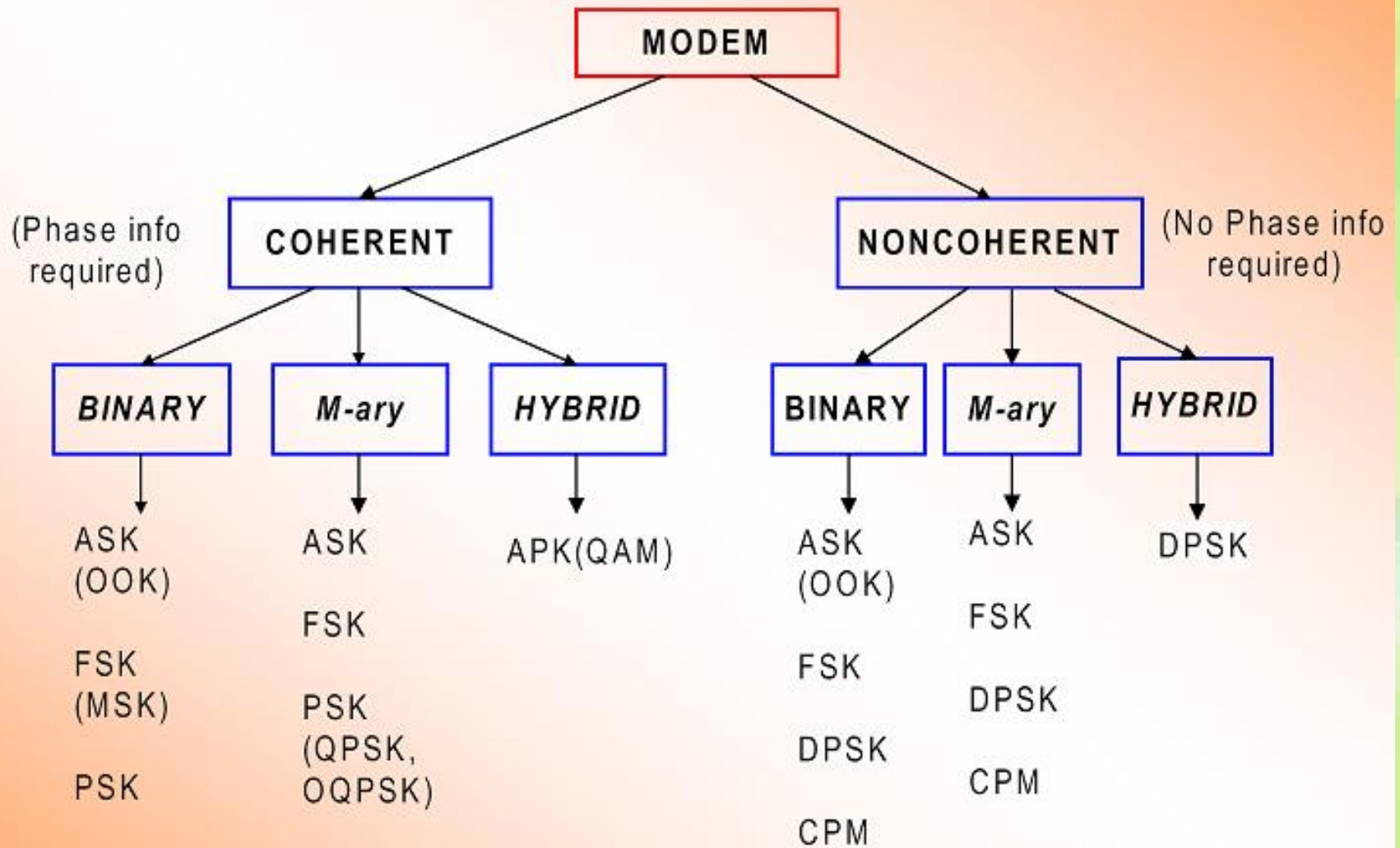
The modulated signal



Digital Modulation Schemes

- Basic Digital Modulation Schemes:
 - Amplitude Shift Keying (ASK)
 - Frequency Shift Keying (FSK)
 - Phase Shift Keying (PSK)
 - Amplitude Phase Keying (APK)
- For Binary signals ($M = 2$), we have
 - Binary Amplitude Shift Keying (BASK)
 - Binary Phase Shift Keying (BPSK)
 - Binary Frequency Shift Keying (BFSK)
- For $M > 2$, many variations of the above techniques exist usually classified as M-ary Modulation/detection

Bandpass MOdulation and DEModulation



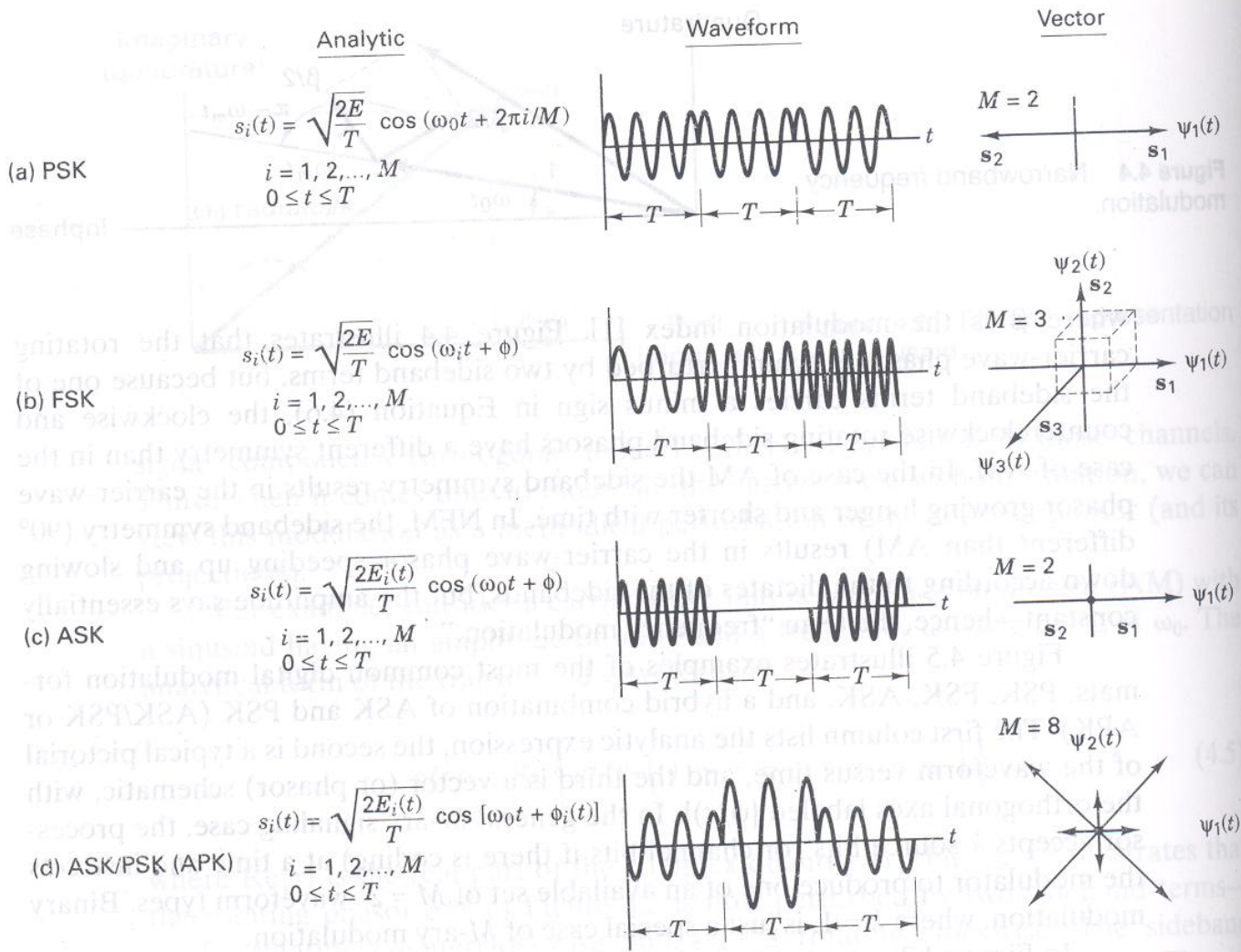
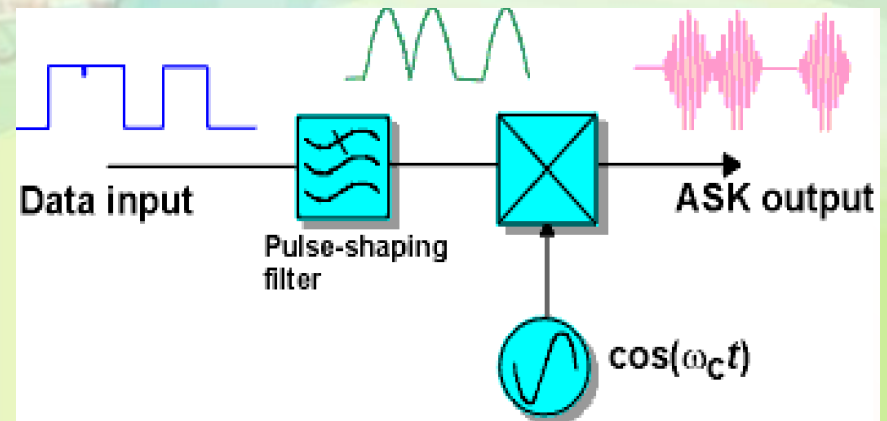
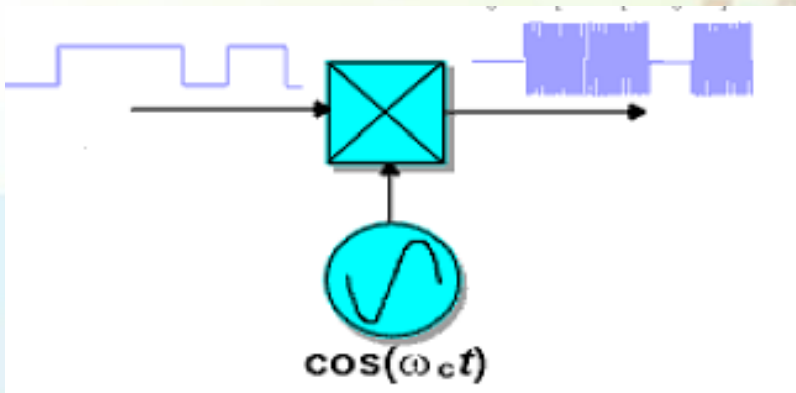
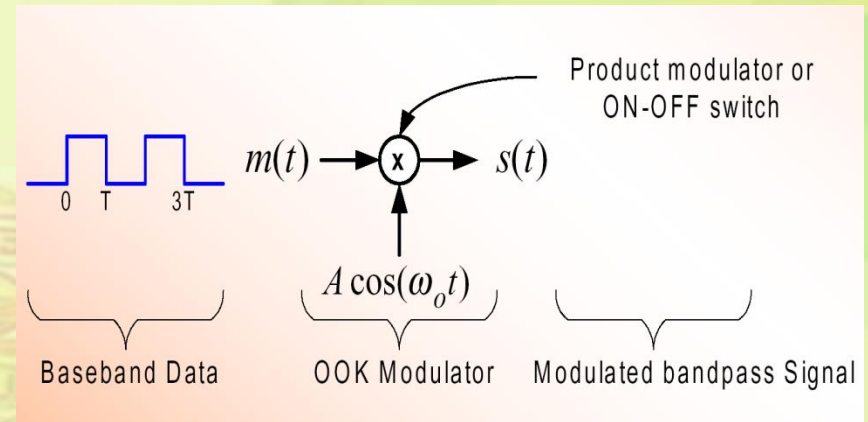


Figure 4.5: digital modulations, (a) PSK (b) FSK (c) ASK (d) ASK/PSK (APK)

Amplitude Shift Keying

- **Modulation Process**

- In Amplitude Shift Keying (**ASK**), the amplitude of the carrier is switched between two (or more) levels according to the digital data
- For BASK (also called **ON-OFF Keying (OOK)**), one and zero are represented by two amplitude levels A_1 and A_0



- **Analytical Expression:**

$$s(t) = \begin{cases} A_i \cos(\omega_c t), & 0 \leq t \leq T \text{ binary } 1 \\ 0, & 0 \leq t \leq T \text{ binary } 0 \end{cases}$$

where A_i = peak amplitude

$$\begin{aligned} s(t) &= A \cos(\omega_0 t) = \sqrt{2} A_{rms} \cos(\omega_0 t) = \sqrt{2 A_{rms}^2} \cos(\omega_0 t) \\ &= \sqrt{2P} \cos(\omega_0 t) = \sqrt{\frac{2E}{T}} \cos(\omega_0 t) \rightarrow P = \frac{V^2}{R} \end{aligned}$$

Hence,

$$s_i(t) = \begin{cases} \sqrt{\frac{2E_i(t)}{T}} \cos(\omega_i t), & 0 \leq t \leq T \text{ binary } 1, \quad i = 0, 2, \dots, M-1 \\ 0, & 0 \leq t \leq T \text{ binary } 0 \end{cases}$$

where

$$E = \int_0^T s_i^2(t) dt, \quad i = 0, 2, \dots, M-1$$

- Where for binary ASK (also known as ON OFF Keying (OOK))

$$s_1(t) = A_c m(t) \cos(\omega_c t + \phi), \quad 0 \leq t \leq T \text{ binary } 1$$

$$s_0(t) = 0, \quad 0 \leq t \leq T \text{ binary } 0$$

- **Mathematical ASK Signal Representation**

- The **complex envelope** of an ASK signal is:

$$g(t) = A_c m(t)$$

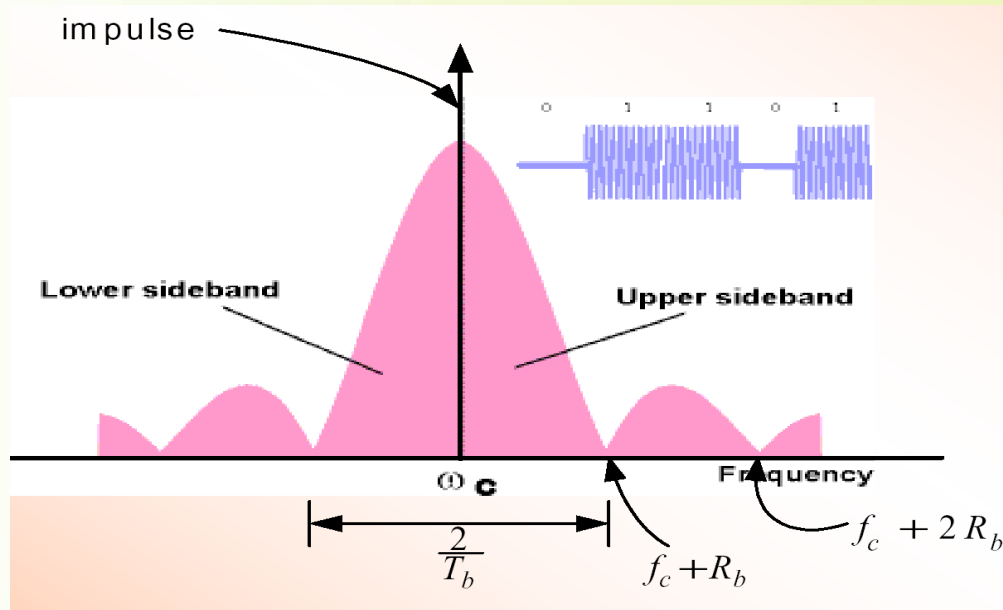
- The **magnitude** and **phase** of an ASK signal are:

$$A(t) = A_c m(t), \quad \phi(t) = 0$$

- The **in-phase** and **quadrature** components are:

$$x(t) = A_c m(t)$$

$$y(t) = 0, \quad \text{the quadrature component is wasted.}$$



It can be seen that the bandwidth of ASK modulated is twice that occupied by the source baseband stream

- **Bandwidth of ASK**

- Bandwidth of ASK can be found from its power spectral density
- The bandwidth of an ASK signal is twice that of the unipolar NRZ line code used to create it., i.e.,

$$B = 2R_b = \frac{2}{T_b}$$

- This is the **null-to-null bandwidth** of ASK

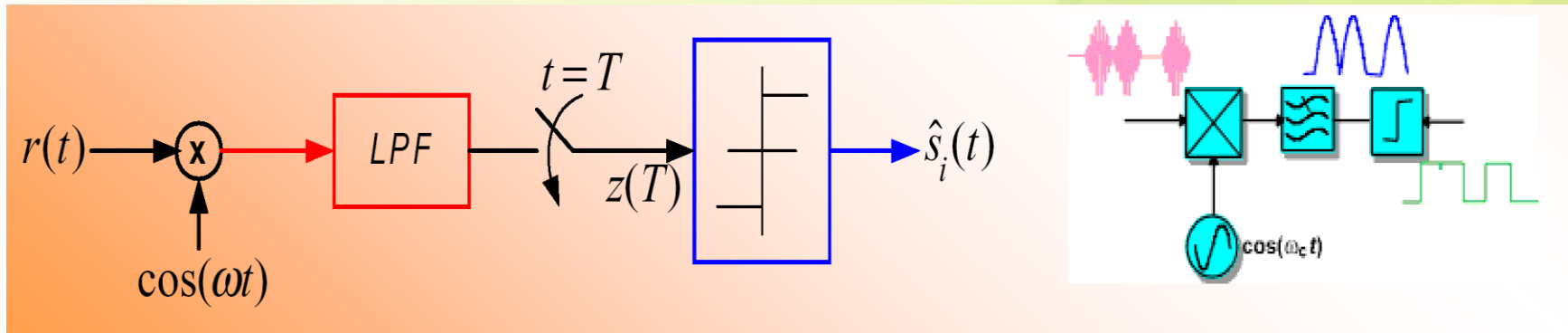
- If raised cosine rolloff pulse shaping is used, then the bandwidth is:

$$B = (1 + r)R_b \Rightarrow W = \frac{1}{2} (1 + r)R_b$$

- Spectral efficiency of ASK is half that of a baseband unipolar NRZ line code
 - This is because the quadrature component is wasted
- 95% energy bandwidth

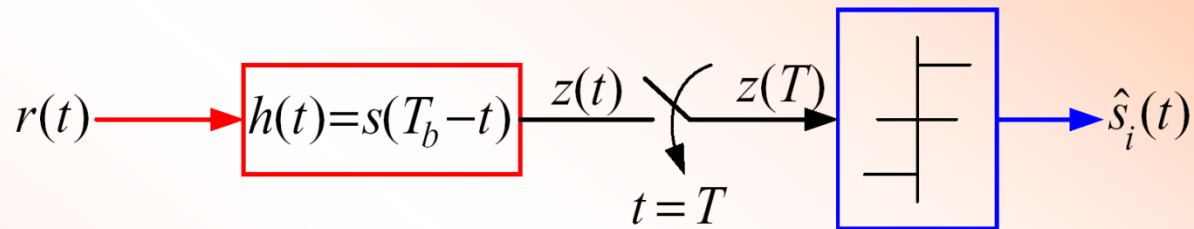
$$B = \frac{3}{T_b} = 3R_b$$

Detectors for ASK Coherent Receiver

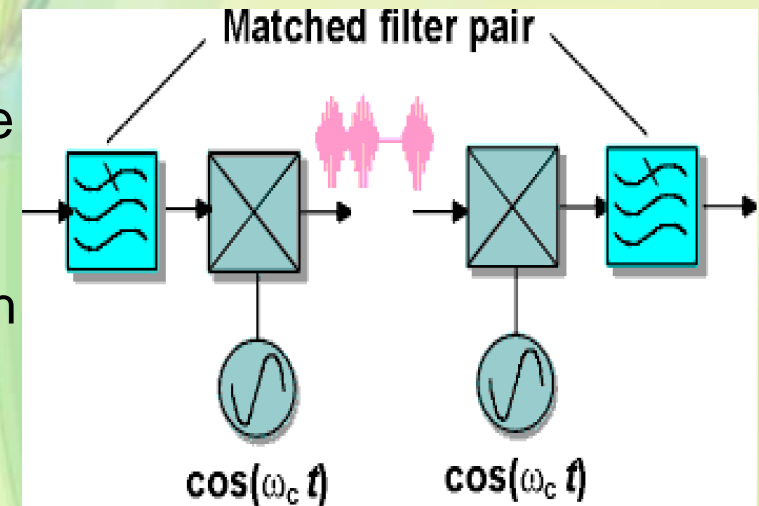


- Coherent detection requires the phase information
- A coherent detector mixes the incoming signal with a locally generated carrier reference
- Multiplying the received signal $r(t)$ by the receiver local oscillator (say $A_c \cos(\omega_c t)$) yields a signal with a baseband component plus a component at $2f_c$
- Passing this signal through a low pass filter eliminates the high frequency component
 - In practice an integrator is used as the LPF

- The output of the LPF is sampled once per bit period
- This sample $z(T)$ is applied to a decision rule
 - $z(T)$ is called the **decision statistic**
- Matched filter receiver of OOK signal



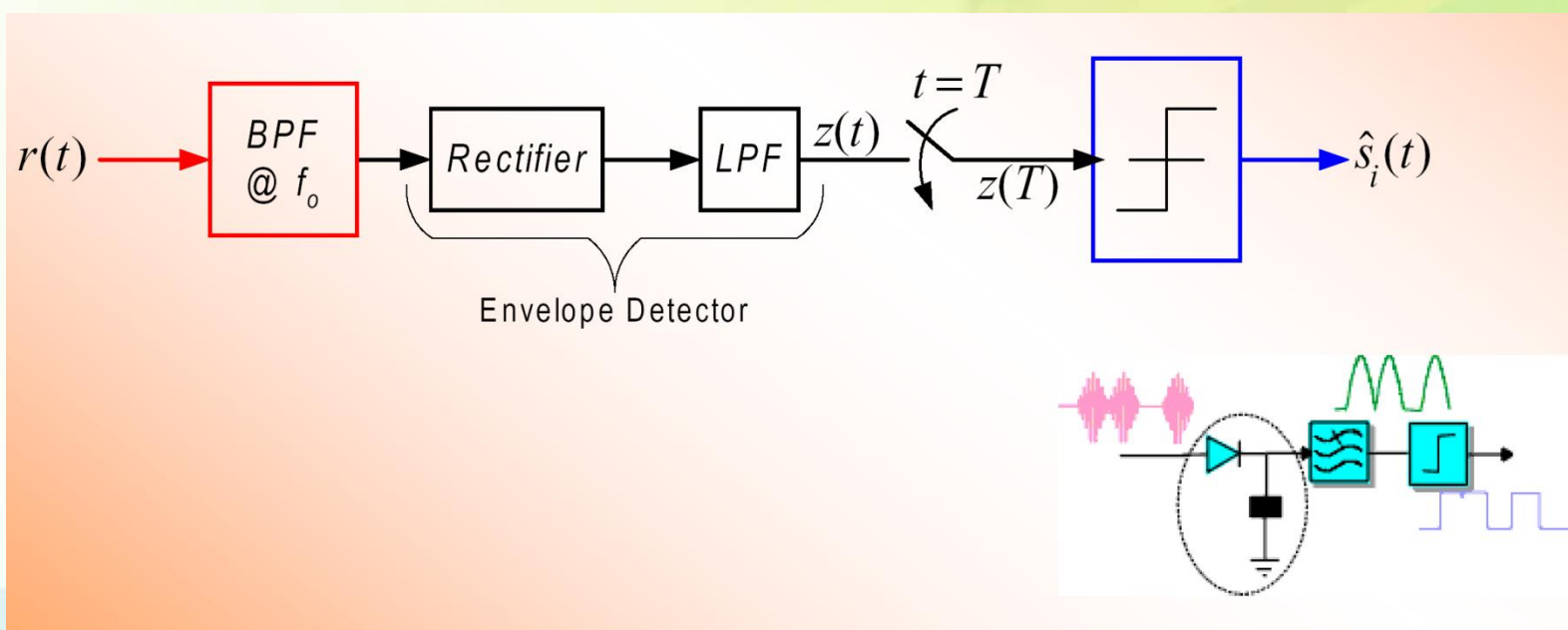
- A MF pair such as the root raised cosine filter can thus be used to shape the source and received baseband symbols
- In fact this is a very common approach in signal detection in most bandpass data modems



Noncoherent Receiver

- Does not require a phase reference at the receiver
- If we do not know the phase and frequency of the carrier, we can use a **noncoherent receiver to recover ASK signal**

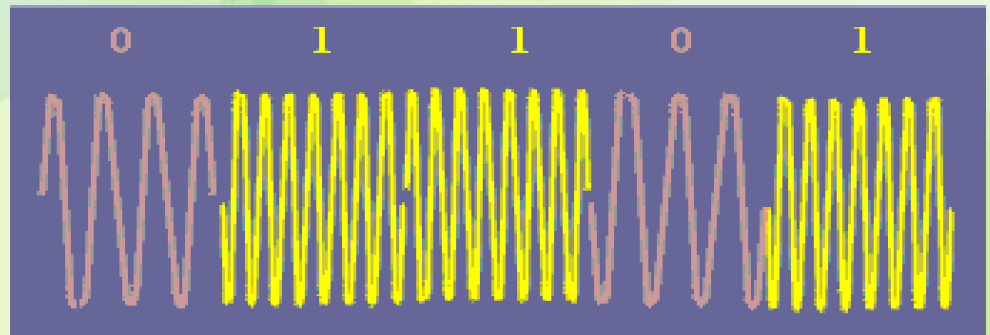
- **Envelope Detector:**



- The simplest implementation of an envelope detector comprises a diode rectifier and smoothing filter

Frequency Shift Keying (FSK)

- In *FSK*, the instantaneous carrier frequency is switched between 2 or more levels according to the baseband digital data
 - data bits select a carrier at one of two frequencies
 - the data is encoded in the frequency
- Until recently, FSK has been the most widely used form of digital modulation; Why?
 - Simple both to generate and detect
 - Insensitive to amplitude fluctuations in the channel
- FSK conveys the data using distinct carrier frequencies to represent symbol states
- An important property of FSK is that the *amplitude of the modulated wave is constant*
- **Waveform**



- **Analytical Expression**

$$s_i(t) = \sqrt{\frac{2E_s}{T_s}} \cos(\underbrace{\omega_i t + \phi}_{\theta_i(t)}), \quad i = 0, 1, \dots, M - 1$$

$$\theta_i(t) = [\omega_0 t + \omega_d \int_{-\infty}^t m(\tau) d\tau]$$

$$f_i = \frac{d}{dt} \theta_i(t) = f_0 + f_d m(t)$$

} Analog form

- General expression is

$$s_i(t) = \sqrt{\frac{2E_s}{T_s}} \cos(2\pi f_0 t + 2\pi i \Delta f t), \quad i = 0, 1, \dots, M - 1$$

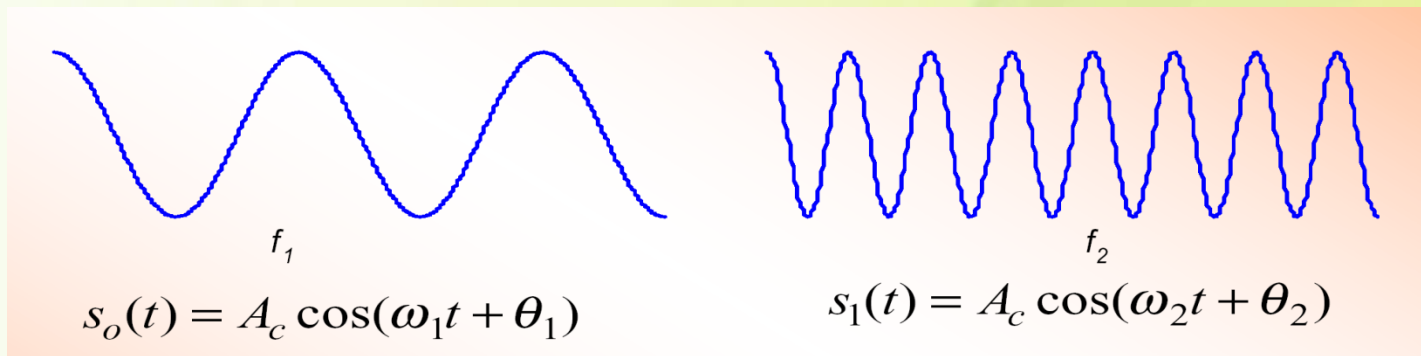
Where

$$\Delta f = f_i - f_{i-1}$$

$$f_i = f_0 + i \Delta f \quad \text{and} \quad E_s = k E_b, \quad T_s = k T_b$$

Binary FSK

- In **BFSK**, 2 different frequencies, f_1 and $f_2 = f_1 + \Delta f$ are used to transmit binary information



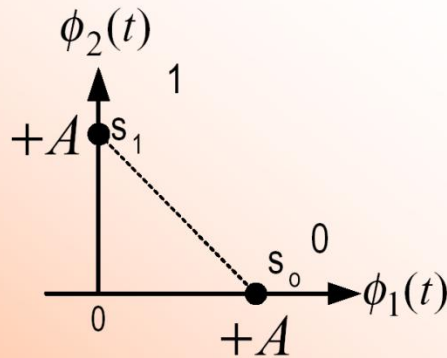
- Data is encoded in the frequencies
- That is, $m(t)$ is used to select between 2 frequencies:
- f_1 is the mark frequency, and f_2 is the space frequency

$$s_0(t) = \sqrt{\frac{2E_s}{T_b}} \cos 2\pi(f_1 + \theta_1), \quad 0 \leq t \leq T_b$$

$$s_1(t) = \sqrt{\frac{2E_s}{T_b}} \cos 2\pi(f_2 + \theta_2), \quad 0 \leq t \leq T_b$$

$$s(t) = \begin{cases} A_c \cos(\omega_1 t + \theta_1), & \text{when } m(t) = +1 \text{ or } X_n = 1 \\ A_c \cos(\omega_2 t + \theta_2), & \text{when } m(t) = -1 \text{ or } X_n = 0 \end{cases}$$

- **Binary Orthogonal Phase FSK**



$$\phi_1(t) = \sqrt{\frac{2E}{T}} \cos(\omega_1 t + \theta_1)$$

$$\phi_2(t) = \sqrt{\frac{2E}{T}} \cos(\omega_2 t + \theta_2)$$

- When ω_0 and ω_1 are chosen so that $\phi_1(t)$ and $\phi_2(t)$ are orthogonal, i.e.,

$$\int_{-\infty}^{\infty} \phi_1(t) \phi_2(t) dt = 0$$

– form a set of $K = 2$ basis orthonormal basis functions

Phase Shift Keying (PSK)

- General expression is

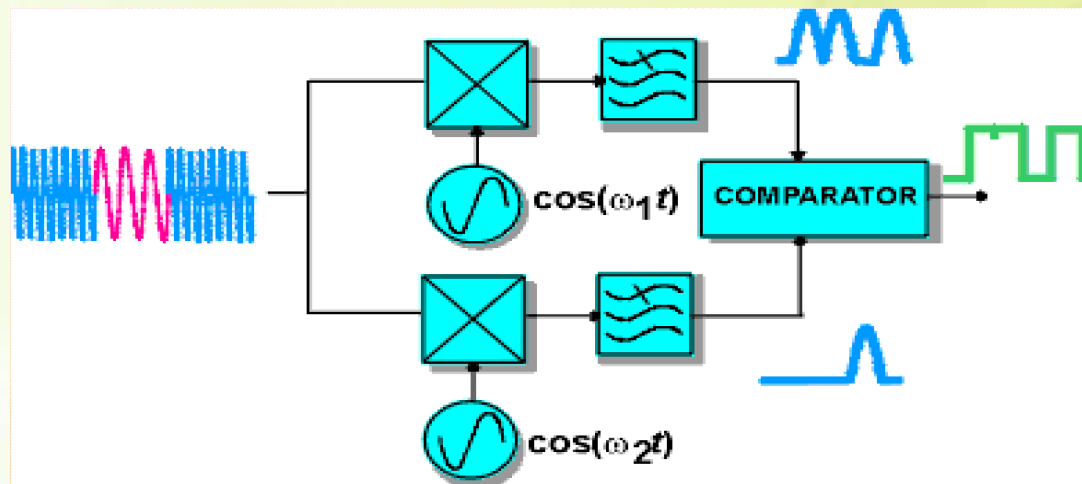
$$s_i(t) = \sqrt{\frac{2E_s}{T_s}} \cos[2\pi f_0 t + \phi_i(t)], \quad i = 0, 1, \dots, M - 1$$

- Where

$$\phi_i(t) = \frac{2\pi i}{M} \quad i = 0, 1, \dots, M - 1$$

Coherent Detection of Binary FSK

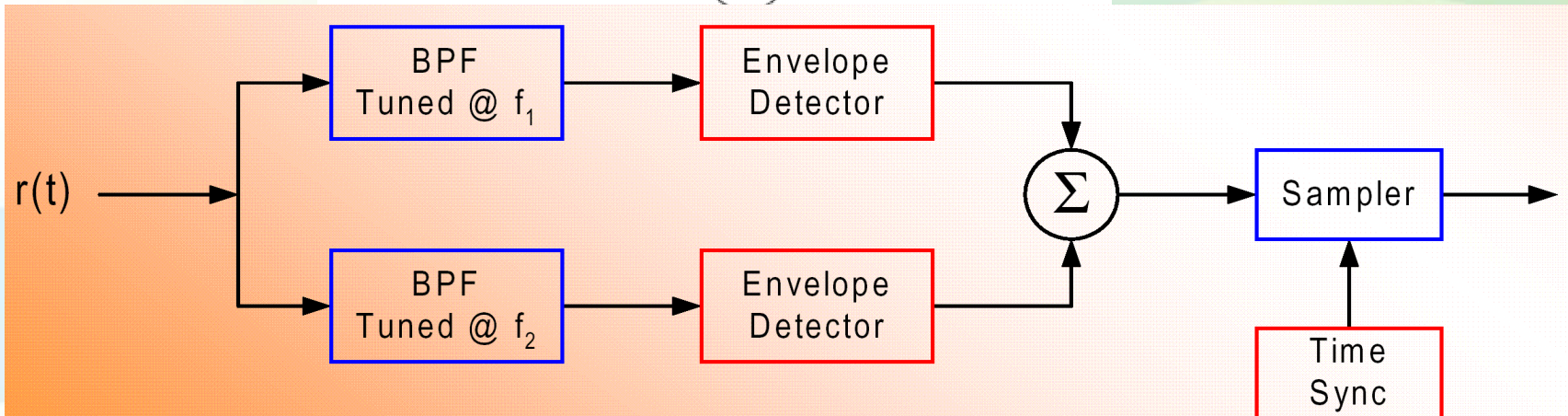
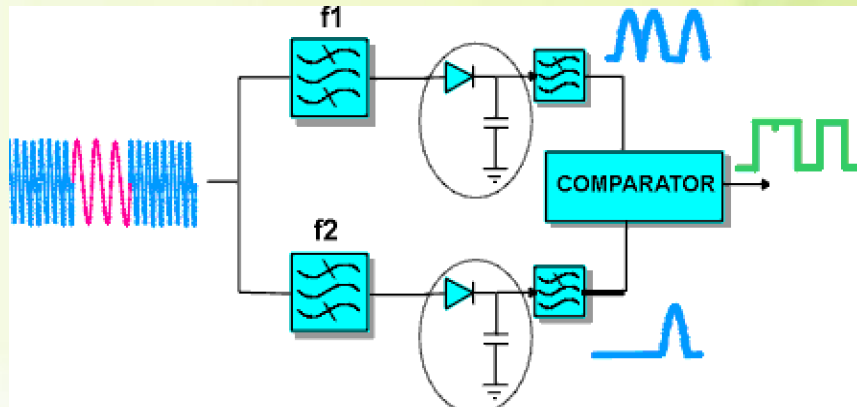
- Coherent detection of Binary FSK is similar to that for ASK but in this case there are 2 detectors tuned to the 2 carrier frequencies



- Recovery of f_c in receiver is made simple if the frequency spacing between symbols is made equal to the ***symbol rate***.

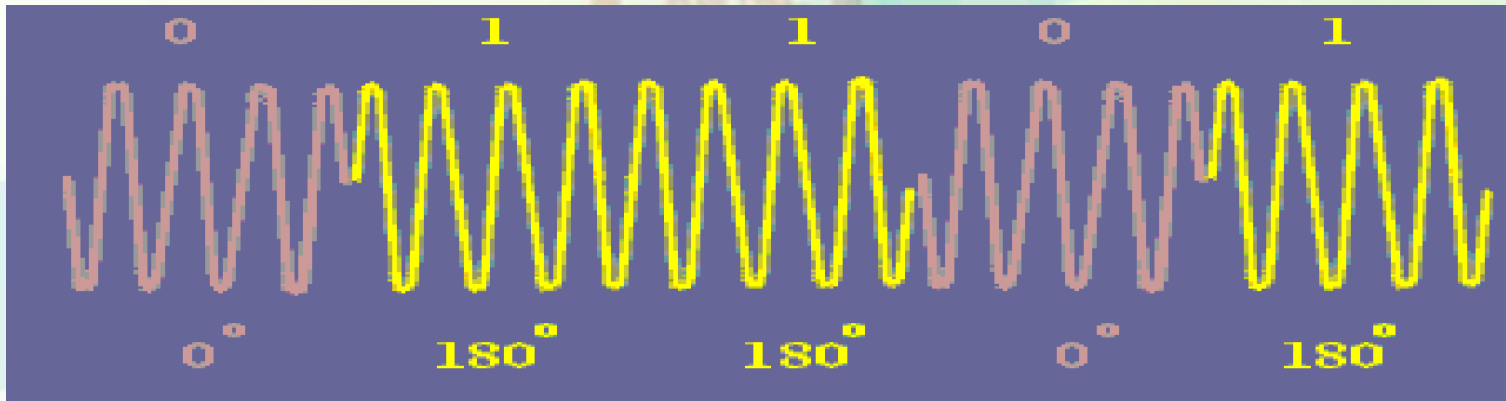
Non-coherent Detection

- One of the simplest ways of detecting binary FSK is to pass the signal through 2 BPF tuned to the 2 signaling freqs and detect which has the larger output averaged over a symbol period



Phase Shift Keying (PSK)

- In PSK, the phase of the carrier signal is switched between 2 (for BPSK) or more (for MPSK) in response to the baseband digital data
- With PSK the information is contained in the instantaneous phase of the modulated carrier
- Usually this phase is imposed and measured with respect to a fixed carrier of known phase – Coherent PSK
- For binary PSK, phase states of 0° and 180° are used
- **Waveform:**



- Analytical expression can be written as

$$s_i(t) = A g(t) \cos[\omega_c t + \phi_i(t)], \quad 0 \leq t \leq T_b, \quad i = 1, 2, \dots, M$$

where

- $g(t)$ is signal pulse shape
- A = amplitude of the signal
- ϕ = carrier phase
- The range of the carrier phase can be determined using

$$\phi_i(t) = \frac{2\pi(i-1)}{M} \quad i = 1, \dots, M$$

- For a rectangular pulse, we obtain

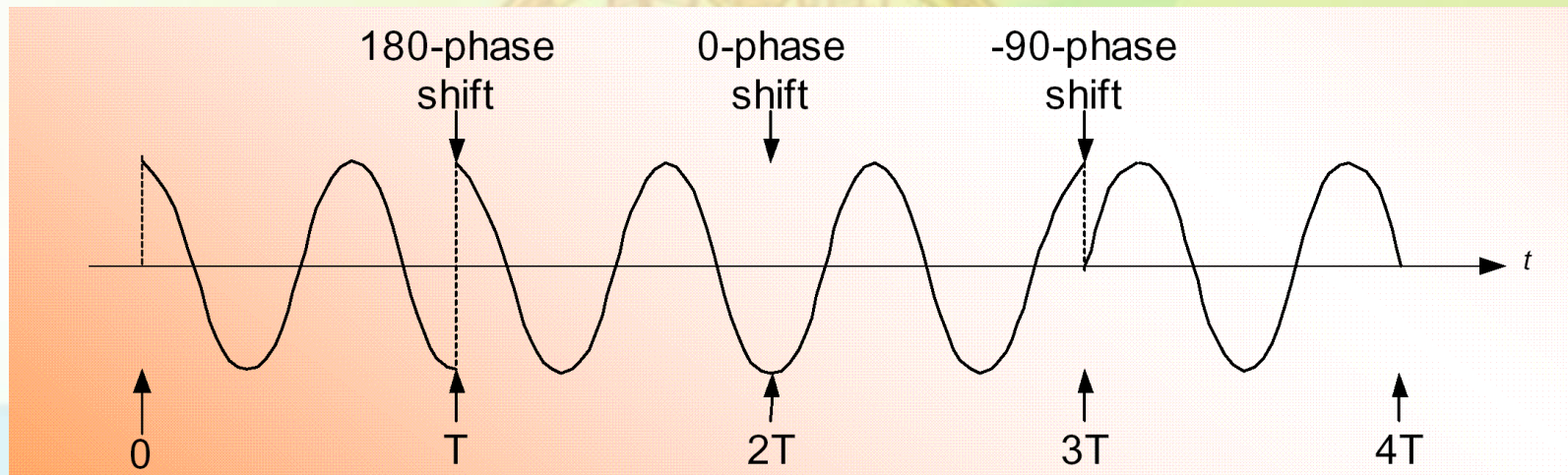
$$g(t) = \sqrt{\frac{2}{T_b}}, \quad 0 \leq t \leq T_b; \quad \text{and assume } A = \sqrt{E_b}$$

- We can now write the analytical expression as

$$s_i(t) = \underbrace{\sqrt{\frac{2E_b}{T_b}}}_{\text{Constant envelope}} \cos\left(\omega_c t + \frac{2\pi(i-1)}{M}\right), \quad 0 \leq t \leq T_b, \quad \text{and } i = 1, 2, \dots, M$$

Constant envelope

carrier phase changes abruptly at the beginning of each signal interval



- In PSK the carrier phase changes abruptly at the beginning of each signal interval while the amplitude remains constant

- We can also write a PSK signal as:

$$s_i(t) = \sqrt{\frac{2E}{T}} \cos\left(\omega_c t + \frac{2\pi(i-1)}{M}\right)$$

$$= \sqrt{\frac{2E}{T}} \left[\cos \frac{2\pi(i-1)}{M} \cos \omega_c t - \sin \frac{2\pi(i-1)}{M} \sin \cos \omega_c t \right]$$

- Furthermore, $s_1(t)$ may be represented as a linear combination of two orthogonal functions $\psi_1(t)$ and $\psi_2(t)$ as follows

$$s_i(t) = \sqrt{E} \cos \frac{2\pi(i-1)}{M} \psi_1(t) - \sqrt{E} \sin \frac{2\pi(i-1)}{M} \psi_2(t)$$

Where

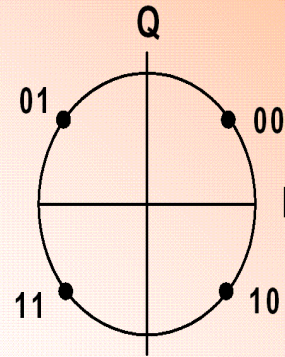
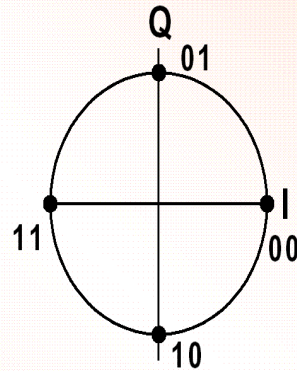
$$\psi_1(t) = \sqrt{\frac{2}{T}} \cos[\omega_c t] \quad \text{and} \quad \psi_2(t) = \sqrt{\frac{2}{T}} \sin[\omega_c t]$$

- Using the concept of the orthogonal basis function, we can represent PSK signals as a two dimensional vector

$$s_i(t) = \left(\sqrt{E_b} \cos \frac{2\pi(i-1)}{M} \psi_1, \sqrt{E_b} \sin \frac{2\pi(i-1)}{M} \psi_2 \right)$$

- For M-ary phase modulation $M = 2^k$, where k is the number of information bits per transmitted symbol
- In an M-ary system, one of $M \geq 2$ possible symbols, $s_1(t), \dots, s_m(t)$, is transmitted during each T_s -second signaling interval
- The mapping or assignment of k information bits into $M = 2^k$ possible phases may be performed in many ways, e.g. for $M = 4$

$$\theta = 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}$$



$$\theta = \frac{\pi}{4}, \frac{3\pi}{4}, \frac{5\pi}{4}, \frac{7\pi}{2}$$

- A preferred assignment is to use “Gray code” in which adjacent phases differ by only one binary digit such that only a single bit error occurs in a k -bit sequence. **Will talk about this in detail in the next few slides.**
- It is also possible to transmit data encoded as the phase change (phase difference) between consecutive symbols
 - This technique is known as Differential PSK (DPSK)
- There is no non-coherent detection equivalent for PSK except for DPSK

M-ary PSK

- In MPSK, the phase of the carrier takes on one of M possible values

$$\phi_i(t) = \frac{2\pi(i-1)}{M}, \quad i = 1, 2, \dots, M$$

- Thus, MPSK waveform is expressed as

$$s_i(t) = \sqrt{\frac{2E}{T}} \cos \left[\omega_0 t + \frac{2\pi(i-1)}{M} \right]$$

$$s_i(t) = g(t) \cos \left[\omega_0 t + \frac{2\pi(i-1)}{M} \right]$$

$M = 2^k$	<i>MPSK</i>
2	<i>BPSK</i>
4	<i>QPSK</i>
8	<i>8-PSK</i>
16	<i>16-PSK</i>
.....	

- Each $s_i(t)$ may be expanded in terms of two basis function $\Psi_1(t)$ and $\Psi_2(t)$ defined as

$$\psi_1(t) = \sqrt{\frac{2}{T_s}} \cos \omega_c t, \quad \psi_2(t) = \sqrt{\frac{2}{T_s}} \sin \omega_c t,$$

Quadrature PSK (QPSK)

- Two BPSK in phase quadrature
- QPSK (or 4PSK) is a modulation technique that transmits 2-bit of information using 4 states of phases
- For example

2-bit Information	ϕ
00	0
01	$\pi/2$
10	π
11	$3\pi/2$

Each symbol corresponds to two bits

- General expression:

$$s_{QPSK}(t) = \sqrt{\frac{2E_s}{T_s}} \cos \left[2\pi f_c t + \frac{2\pi(i-1)}{M} \right], \quad i = 1, 2, 3, 4 \quad 0 \leq t \leq T_s$$

- The signals are:

$$s_0 = \sqrt{\frac{2E_s}{T_s}} \cos(\omega_c t) \quad s_1 = \sqrt{\frac{2E_s}{T_s}} \cos\left(\omega_c t + \frac{\pi}{2}\right) = -\sqrt{\frac{2E_s}{T_s}} \sin(\omega_c t)$$

$$s_2 = \sqrt{\frac{2E_s}{T_s}} \cos(\omega_c t + \pi) = -\sqrt{\frac{2E_s}{T_s}} \cos(\omega_c t)$$

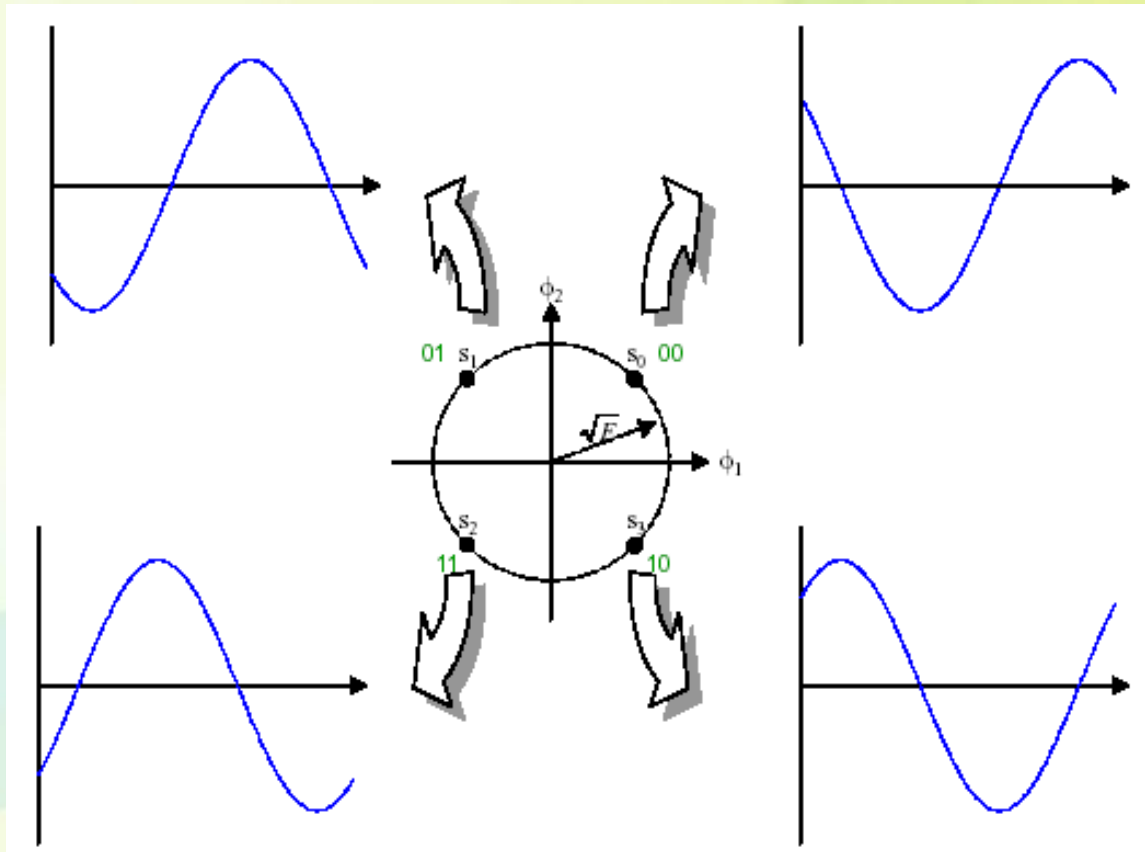
$$s_3 = \sqrt{\frac{2E_s}{T_s}} \cos\left(\omega_c t + \frac{3\pi}{2}\right) = \sqrt{\frac{2E_s}{T_s}} \sin(\omega_c t)$$

$$s_{0,2}(t) = \pm \sqrt{\frac{2E_s}{T_s}} \cos \omega_c t, \quad \phi - \text{shift of } 0^\circ \text{ and } 180^\circ$$

$$s_{1,3}(t) = \pm \sqrt{\frac{2E_s}{T_s}} \sin \omega_c t, \quad \phi - \text{shift of } 90^\circ \text{ and } 270^\circ$$

- We can also have:

$$s_{QPSK}(t) = \sqrt{\frac{2E_s}{T_s}} \cos\left[\omega_c t + \frac{2\pi(i-1)}{M} - \frac{\pi}{4}\right], \quad i = 1, 2, 3, 4 \quad 0 \leq t \leq T_s$$



- One of 4 possible waveforms is transmitted during each signaling interval T_s
 - i.e., 2 bits are transmitted per modulation symbol $\rightarrow T_s = 2T_b$)
- In QPSK, both the in-phase and quadrature components are used
- The **I** and **Q** channels are aligned and phase transition occur once every $T_s = 2T_b$ seconds with a maximum transition of 180 degrees
- From

$$s_{QPSK}(t) = \sqrt{\frac{2E_s}{T_s}} \cos \left[2\pi f_c t + \frac{2\pi(i-1)}{M} \right]$$

- As shown earlier we can use trigonometric identities to show that

$$s_{QPSK}(t) = \sqrt{\frac{2E_s}{T_s}} \cos \left[\frac{2\pi(i-1)}{M} \right] \cos(\omega_c t) - \sqrt{\frac{2E_s}{T_s}} \sin \left[\frac{2\pi(i-1)}{M} \right] \sin(\omega_c t)$$

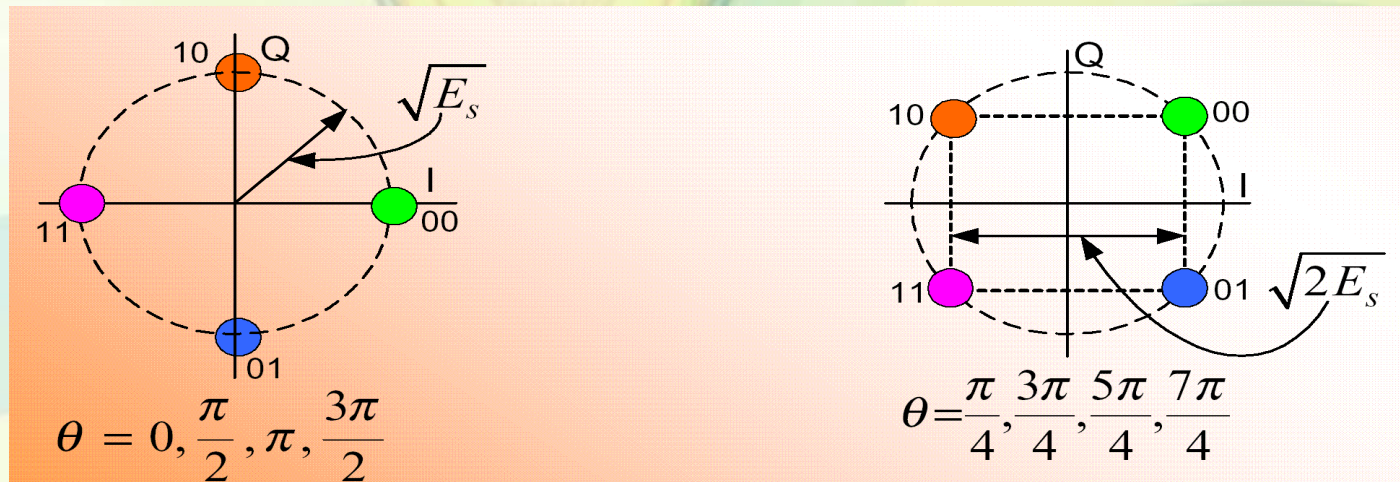
- In terms of basis functions

$$\psi_1(t) = \sqrt{\frac{2}{T_s}} \cos 2\pi f_c t \quad \text{and} \quad \psi_2(t) = \sqrt{\frac{2}{T_s}} \sin 2\pi f_c t$$

we can write $s_{QPSK}(t)$ as

$$s_{QPSK}(t) = \left\{ \sqrt{E_s} \cos \left[\frac{2\pi(i-1)}{M} \right] \psi_1(t) - \sqrt{E_s} \sin \left[\frac{2\pi(i-1)}{M} \right] \psi_2(t) \right\}$$

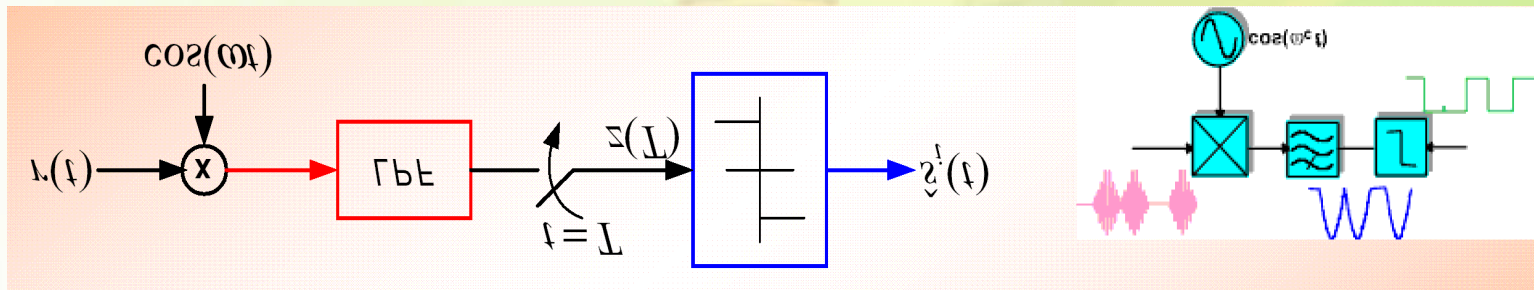
- With this expression, the constellation diagram can easily be drawn
- For example:



Coherent Detection

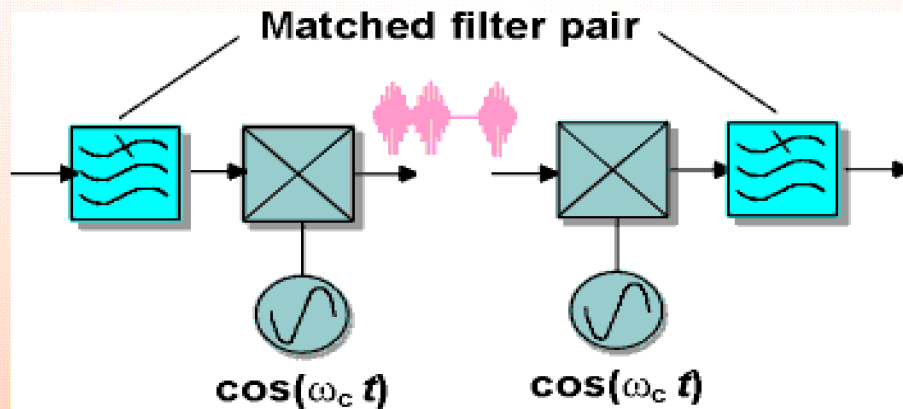
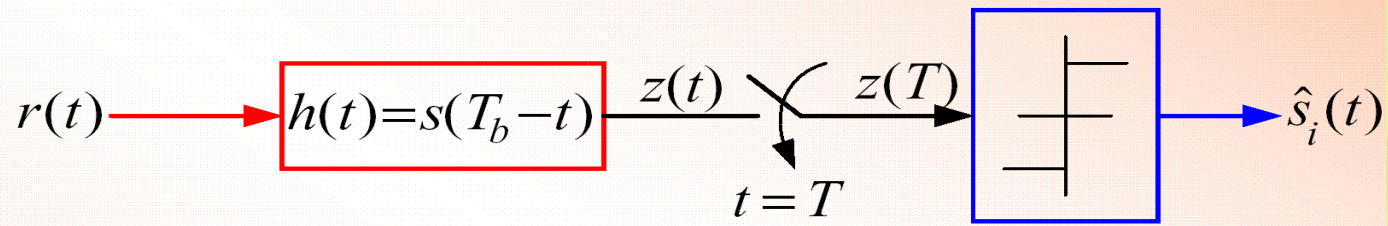
1. Coherent Detection of PSK

- Coherent detection requires the phase information
- A coherent detector operates by mixing the incoming data signal with a locally generated carrier reference and selecting the difference component from the mixer output



- Multiplying $r(t)$ by the receiver LO (say $A \cos(\omega_c t)$) yields a signal with a baseband component plus a component at $2f_c$
- The LPF eliminates the high frequency component
- The output of the LPF is sampled once per bit period
- The sampled value $z(T)$ is applied to a decision rule
 - $z(T)$ is called the **decision statistic**

- Matched filter receiver



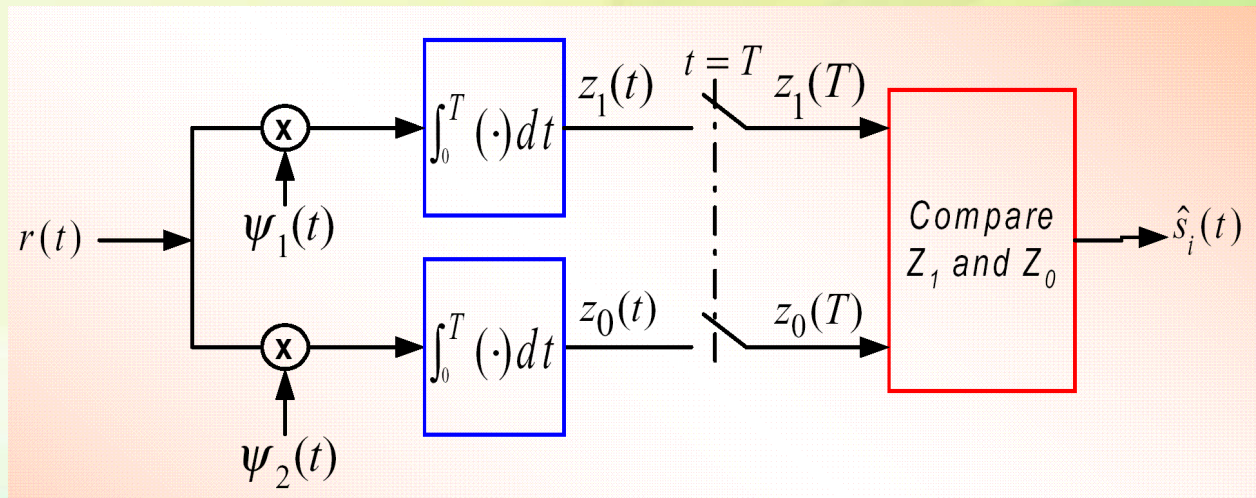
- A MF pair such as the root raised cosine filter can thus be used to shape the source and received baseband symbols
- In fact this is a very common approach in signal detection in most bandpass data modems

2. Coherent Detection of MPSK

- QPSK receiver is composed of 2 BPSK receivers
 - one that locks on to the sine carrier and
 - the other that locks onto the cosine carrier

$$\psi_1(t) = A \cos \omega_0 t$$

$$\psi_2(t) = A \sin \omega_0 t$$



$$z_0(t) = \int_0^{T_s} s_0(t) \psi_1(t) dt = \int_0^{T_s} (A \cos \omega_0 t) (A \cos \omega_0 t) dt = \frac{A^2 T_s}{2} \triangleq L_0$$

$$z_1(t) = \int_0^{T_s} s_0(t) \psi_2(t) dt = \int_0^{T_s} (A \cos \omega_0 t) (A \sin \omega_0 t) dt = 0$$

Output	$S_0(t)$	$S_1(t)$	$S_2(t)$	$S_3(t)$
Z_0	L_0	0	$-L_0$	0
Z_1	0	$-L_0$	0	L_0

$$L_0 = \frac{A^2 T_s}{2} \cos \frac{\pi}{4}$$

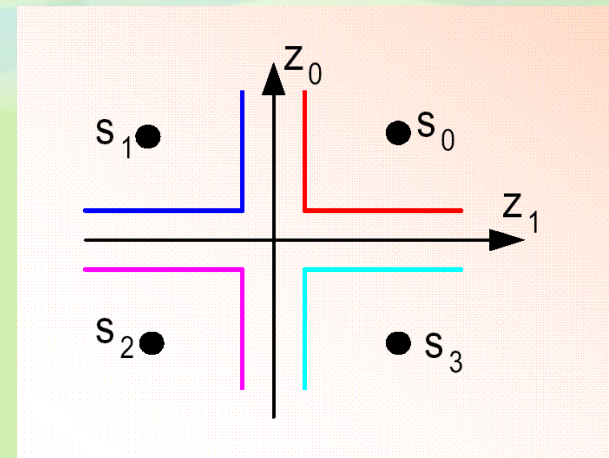
- If $\psi_1(t) = A \cos(\omega_0 t + 45^\circ)$ and $\psi_2(t) = A \cos(\omega_0 t - 45^\circ)$

Output	$S_0(t)$	$S_1(t)$	$S_2(t)$	$S_3(t)$
Z_0	L_0	$-L_0$	$-L_0$	L_0
Z_1	L_0	L_0	$-L_0$	$-L_0$

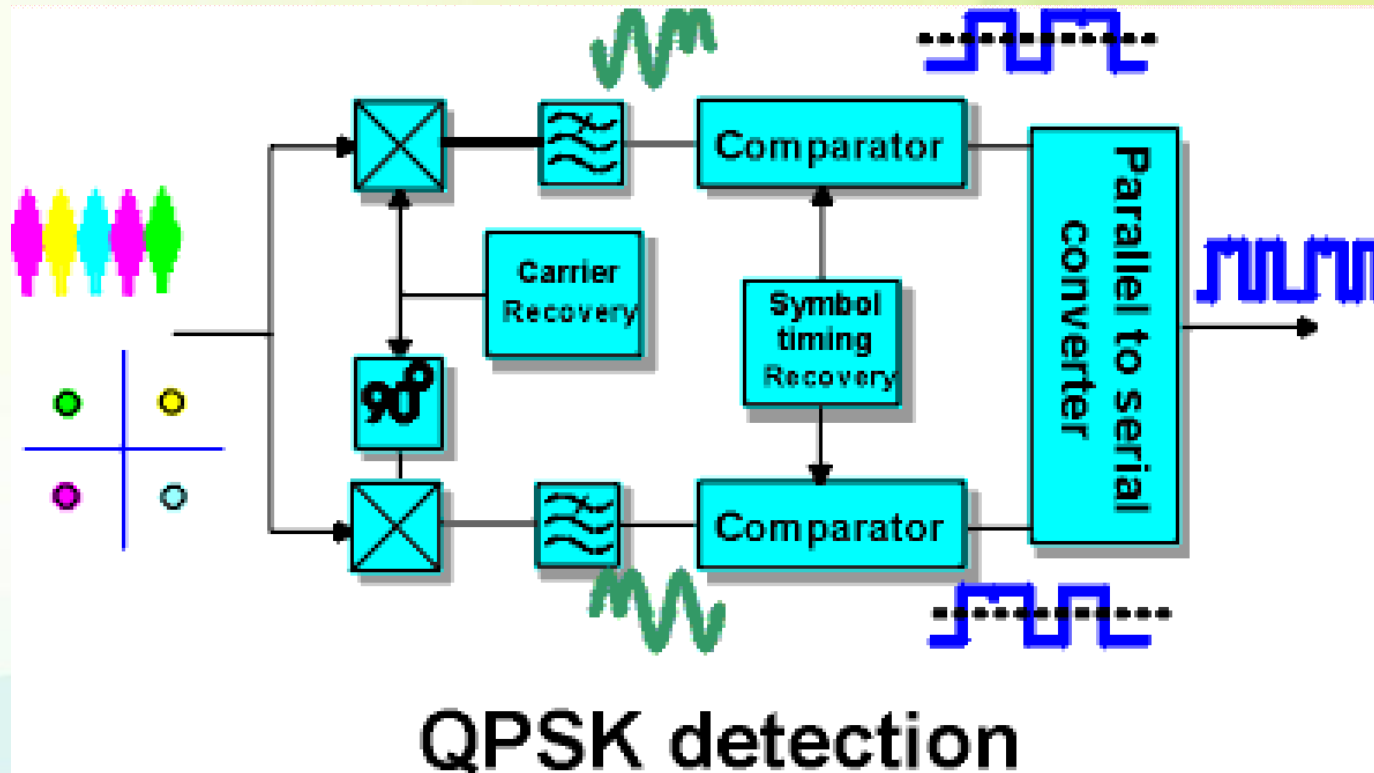
- Decision:
 1. Calculate $z_i(t)$ as

$$z_i(t) = \int_0^T r(t) \psi_i(t) dt$$

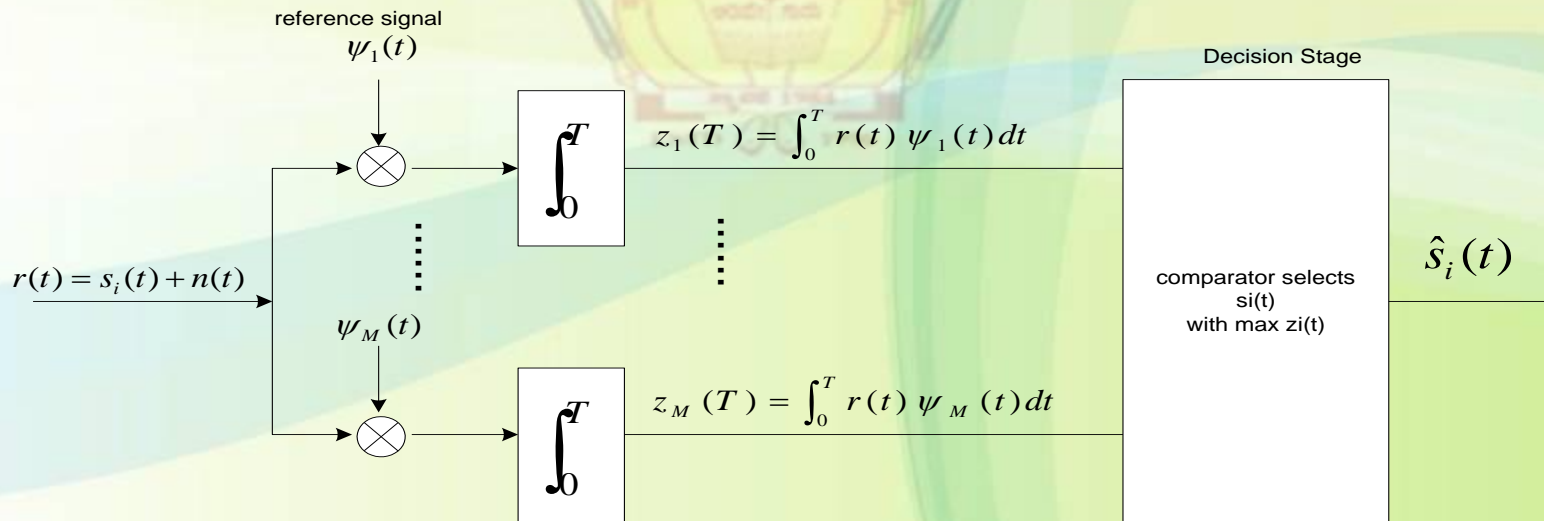
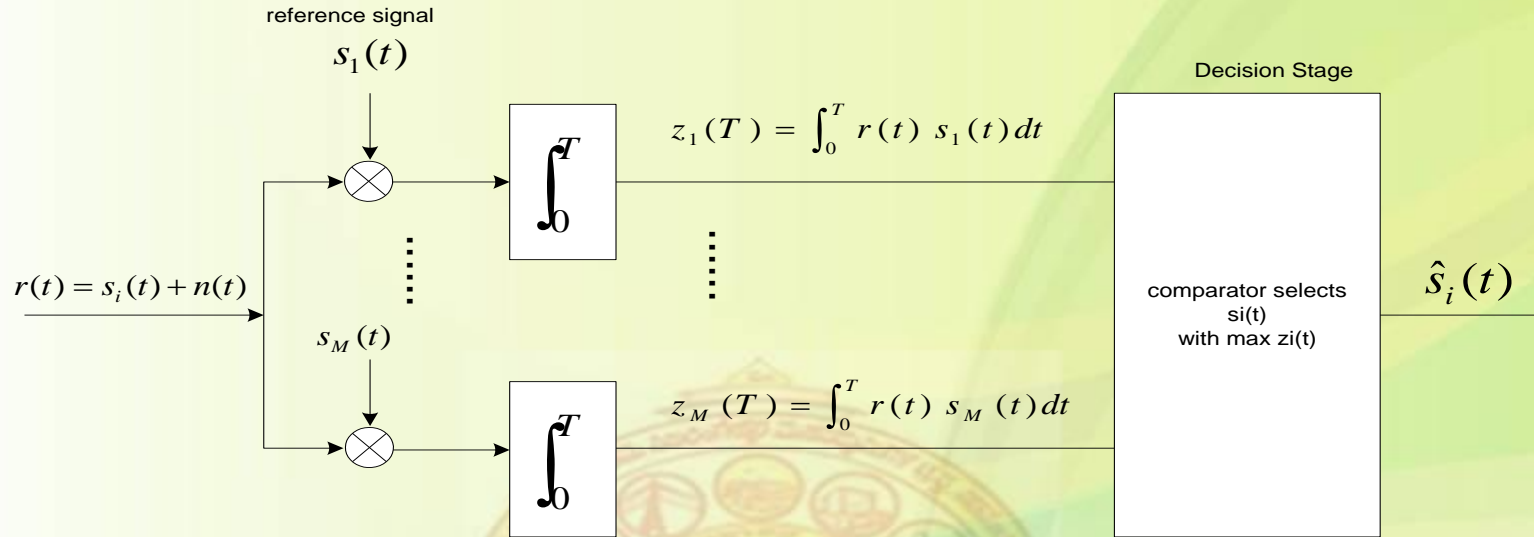
2. Find the quadrant of (Z_0, Z_1)



- A coherent QPSK receiver requires accurate carrier recovery using a 4th power process, to restore the 90° phase states to modulo 2π



Correlation Receiver



Differential Modulation

- In the transmitter, **each symbol is modulated relative to the previous symbol and modulating signal**, for instance in BPSK $0 = \text{no change}$, $1 = +180^\circ$
- In the receiver, the current symbol is demodulated **using the previous symbol as a reference**. The previous symbol serves as an estimate of the channel. A no-change condition causes the modulated signal to remain at the same 0 or 1 state of the previous symbol.

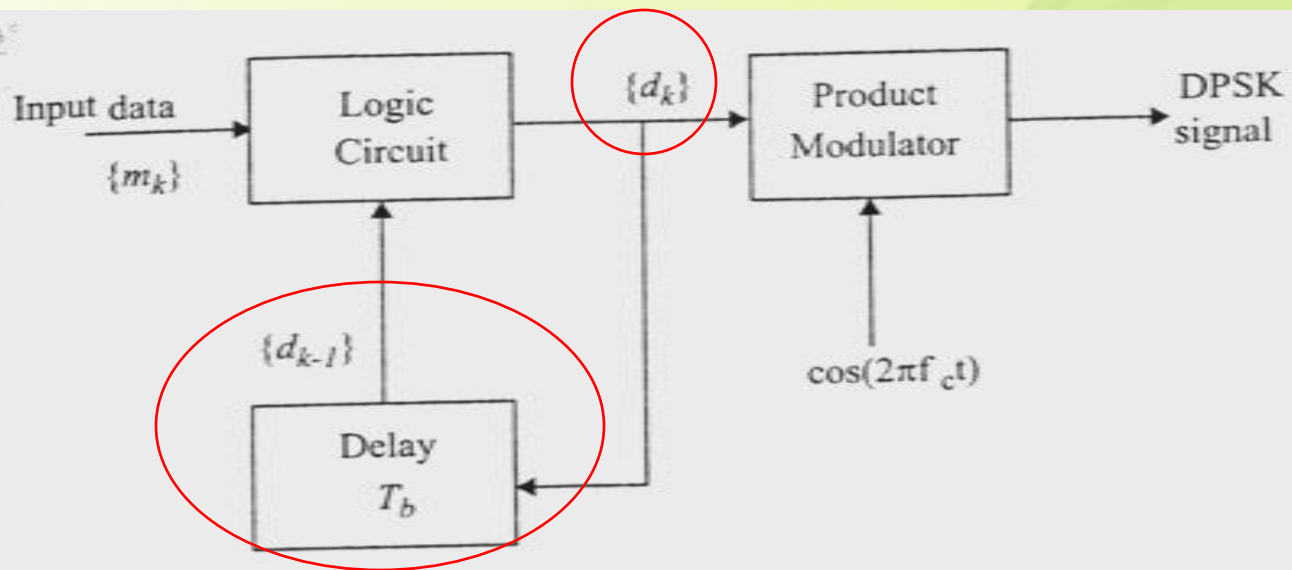


Figure 5.24
Block diagram of a DPSK transmitter.

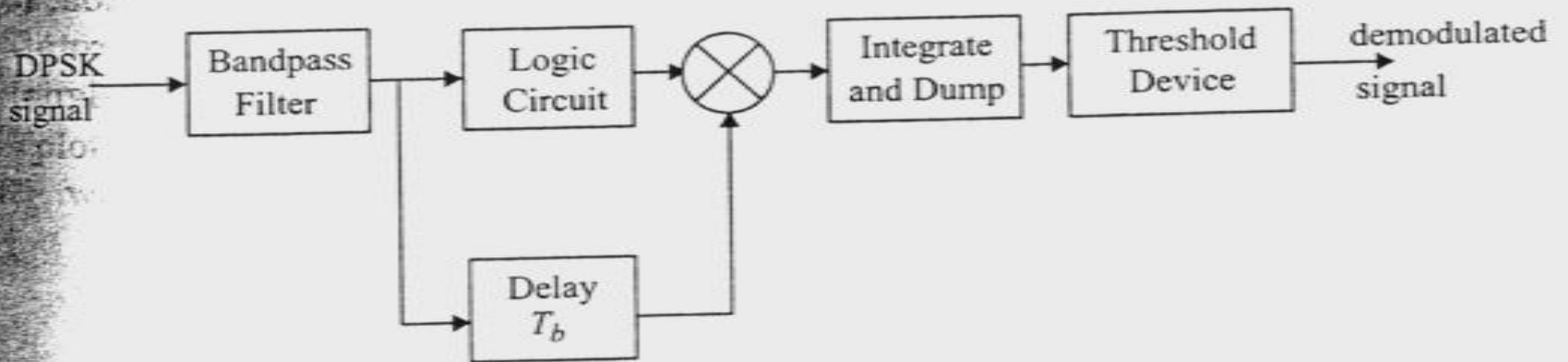


Figure 5.25
Block diagram of DPSK receiver.

Table 5.1 Illustration of the Differential Encoding Process

$\{m_k\}$		1	0	0	1	0	1	1	0
$\{d_{k-1}\}$		1	1	0	1	1	0	0	0
$\{d_k\}$	1	1	0	1	1	0	0	0	1

DPSK

Let $\{d_k\}$ denote the differentially encoded sequence with this added reference bit. We now introduce the following definitions in the generation of this sequence:

- If the incoming binary symbol b_k is **1**, leave the symbol d_k **unchanged** with respect to the previous bit.
- If the incoming binary symbol b_k is **0**, **change** the symbol d_k with respect to the previous bit.

DPSK

- to send symbol 0, we advance the phase of the current signal waveform by 180 degrees,
- to send symbol 1, we leave the phase of the current signal waveform unchanged.

Generation of DPSK:

- The differential encoding process at the transmitter input starts with an arbitrary first bit, serving as reference.

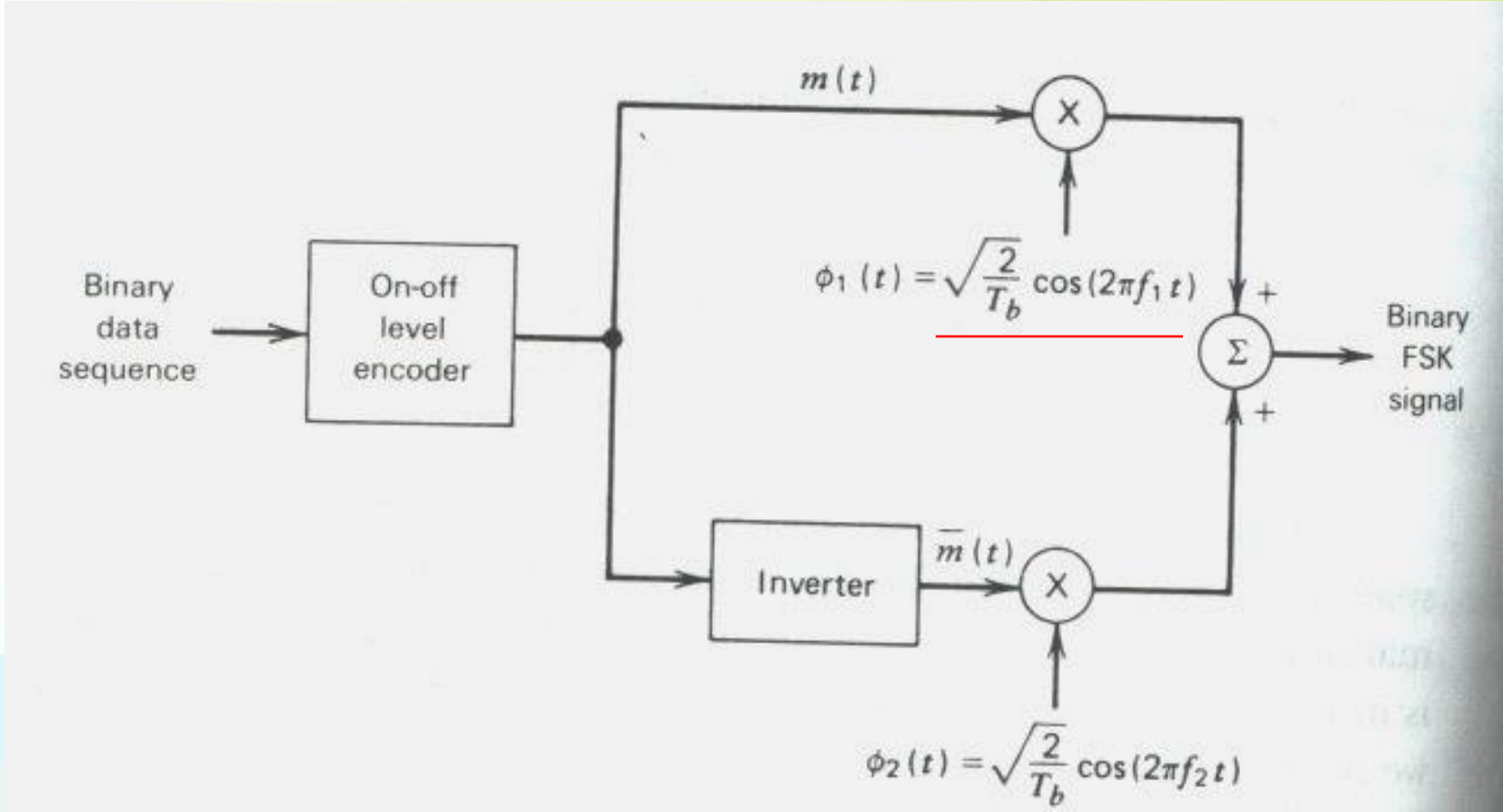
Differential Phase Shift Keying (DPSK):

- DPSK is a **non coherent** form of phase shift keying which avoids the need for a coherent reference signal at the receiver.

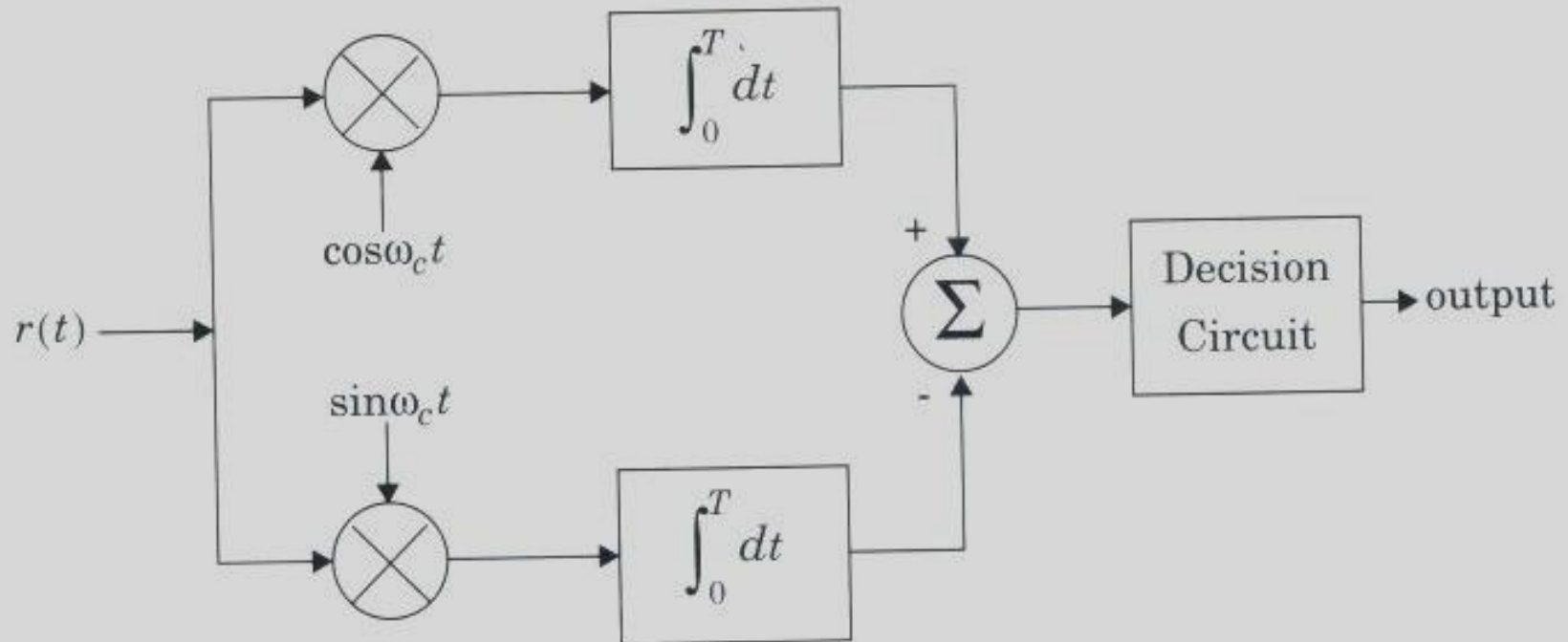
Advantage:

- Non coherent receivers are **easy and cheap to build**, hence widely used in wireless communications.
- DPSK **eliminates the need for a coherent reference signal** at the receiver by combining two basic operations at the transmitter:

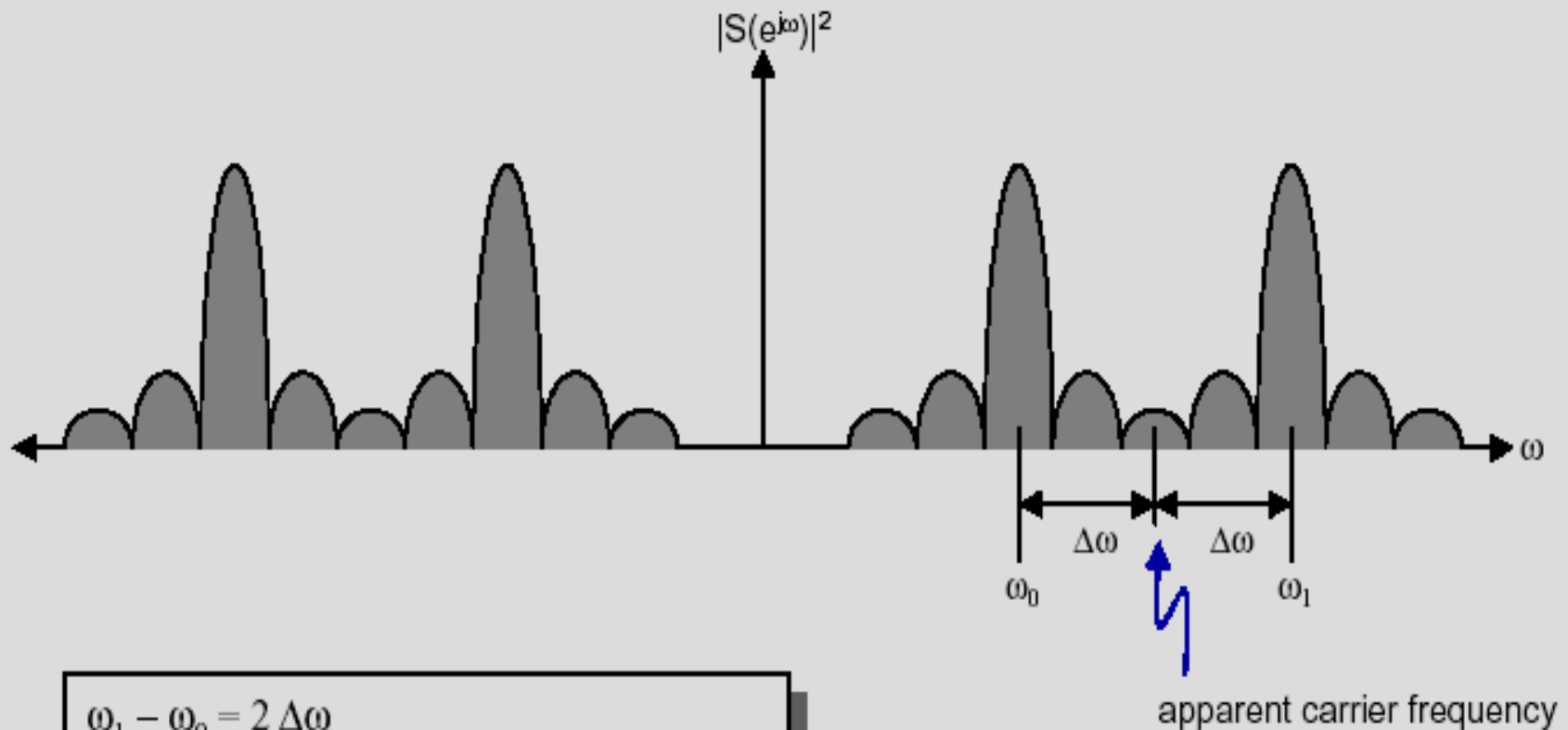
BFSK Transmitter



Coherent Detection Of BFSK



FSK Spectrum



$$\omega_1 - \omega_0 = 2 \Delta\omega$$

where

$\Delta\omega$ = frequency shift from apparent carrier

Minimum Shift Keying (MSK)

MSK is a continuous **phase-frequency** shift keying;



Why MSK?

-- Exploitation of **Phase** Information **besides frequency**.

Representation of a MSK signal

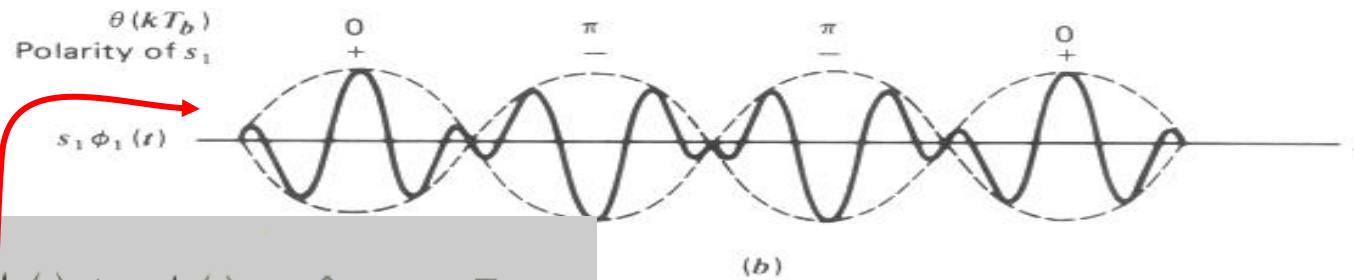
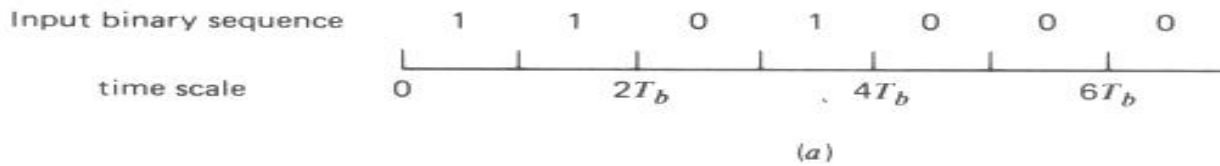
$$s(t) = s_1\phi_1(t) + s_2\phi_2(t) \quad 0 \leq t \leq T_b$$

the appropriate form for the orthonormal basis functions $\phi_1(t)$ and $\phi_2(t)$ is as follows:

$$\phi_1(t) = \sqrt{\frac{2}{T_b}} \cos\left(\frac{\pi}{2T_b} t\right) \cos(2\pi f_c t) \quad -T_b \leq t \leq T_b \quad (7.59)$$

and

$$\phi_2(t) = \sqrt{\frac{2}{T_b}} \sin\left(\frac{\pi}{2T_b} t\right) \sin(2\pi f_c t) \quad 0 \leq t \leq 2T_b \quad (7.60)$$



$$s(t) = s_1\phi_1(t) + s_2\phi_2(t) \quad 0 \leq t \leq T_b$$

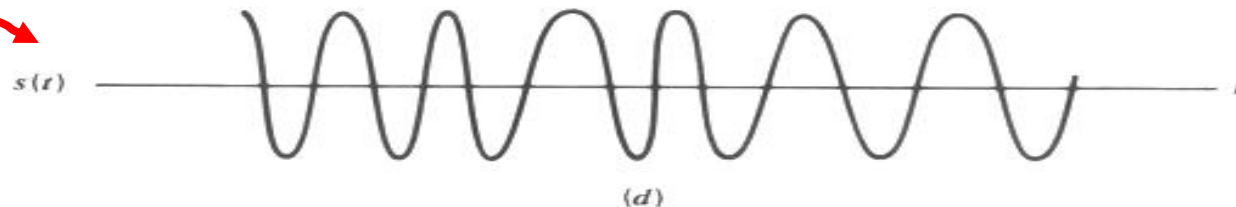
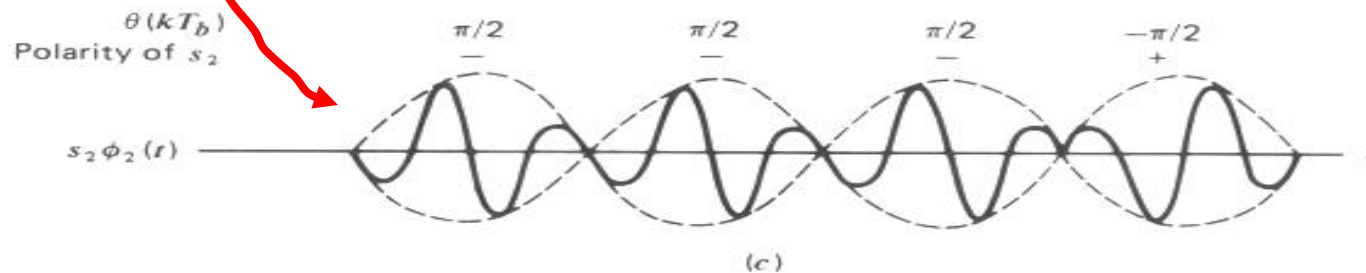
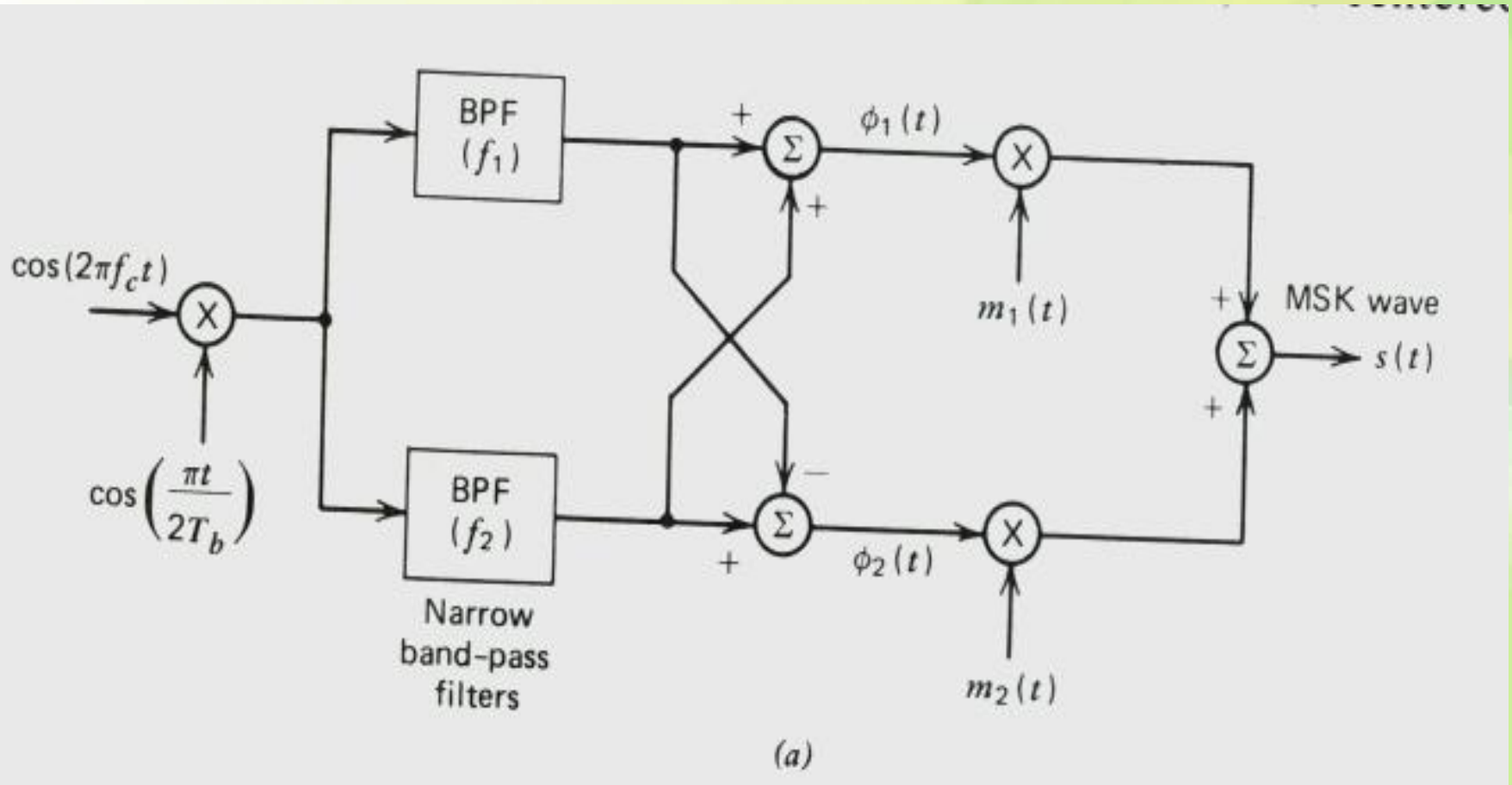
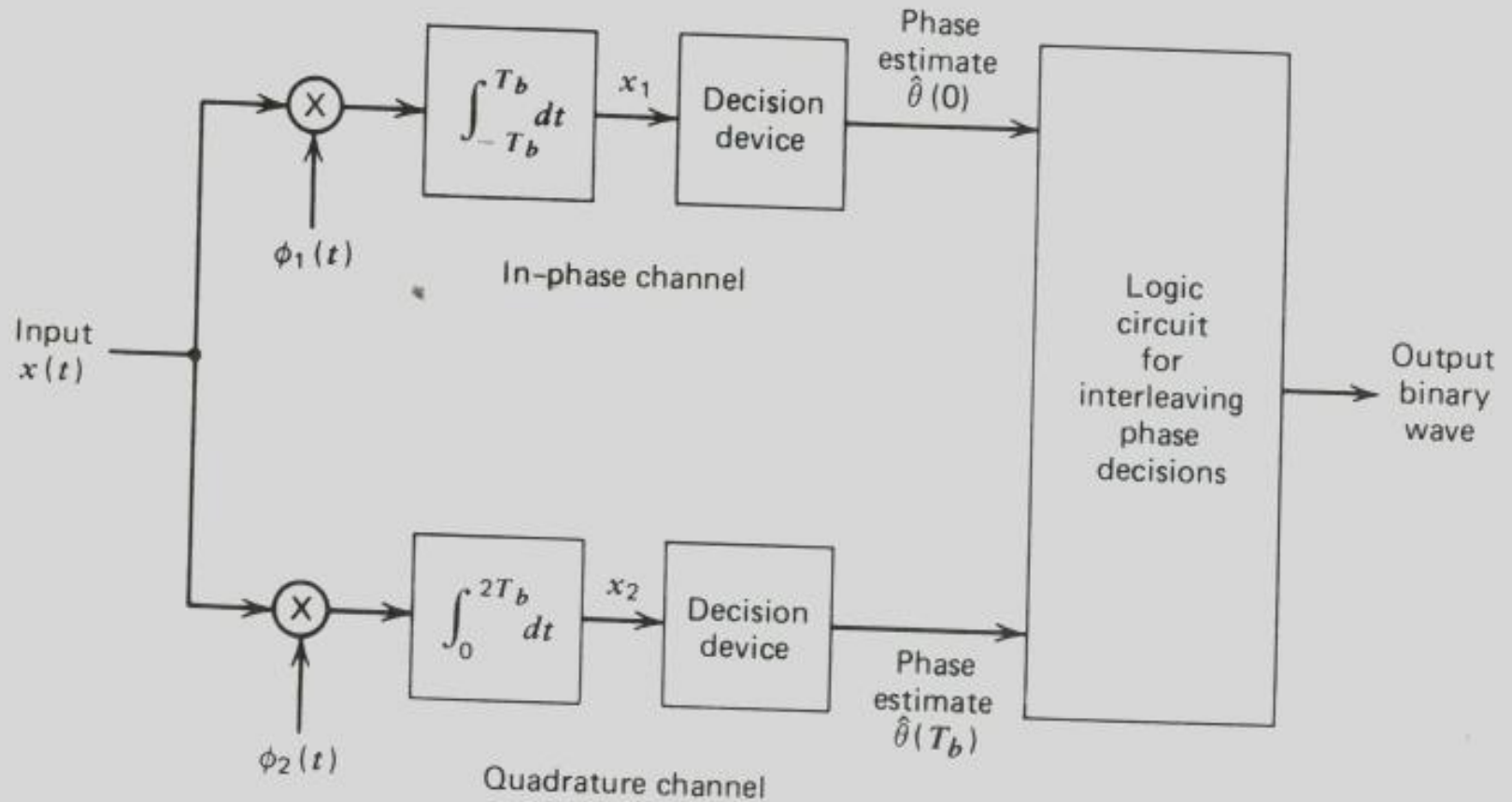


Figure 7.13 Sequence and waveforms for MSK signal. (a) Input binary sequence. (b) Scaled time function $s_1\phi_1(t)$. (c) Scaled time function $s_2\phi_2(t)$. (d) MSK signal $s(t)$ obtained by adding $s_1\phi_1(t)$ and $s_2\phi_2(t)$ on a bit-by-bit basis.

MSK Transmitter



MSK Receiver



M-ary Quadrature Amplitude Modulation (QAM)

- It's a Hybrid modulation
- As we allow the amplitude to also vary with the phase, a new modulation scheme called quadrature amplitude modulation (QAM) is obtained.
- The constellation diagram of 16-ary QAM consists of a square lattice of signal points.

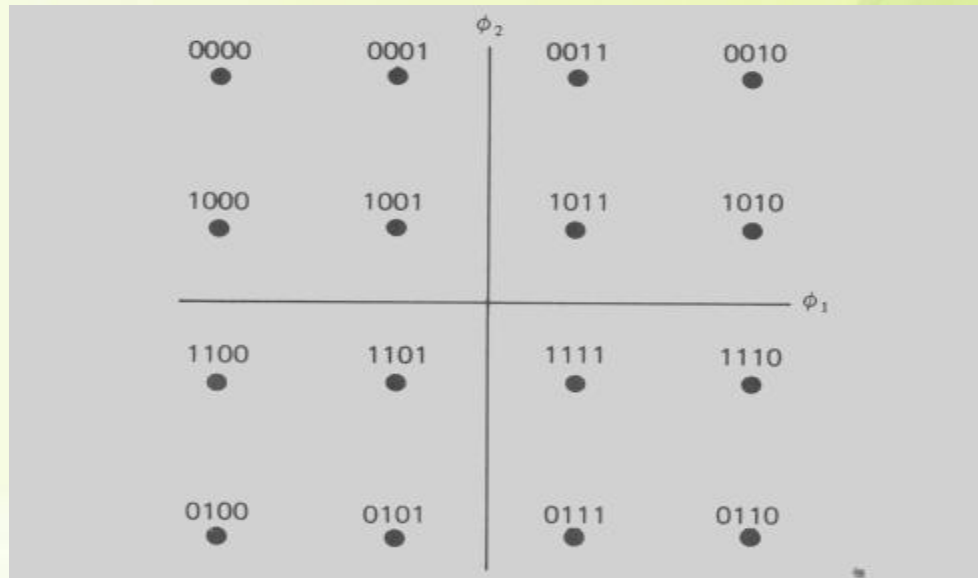


Fig: signal Constellation of M-ary QAM for M=16

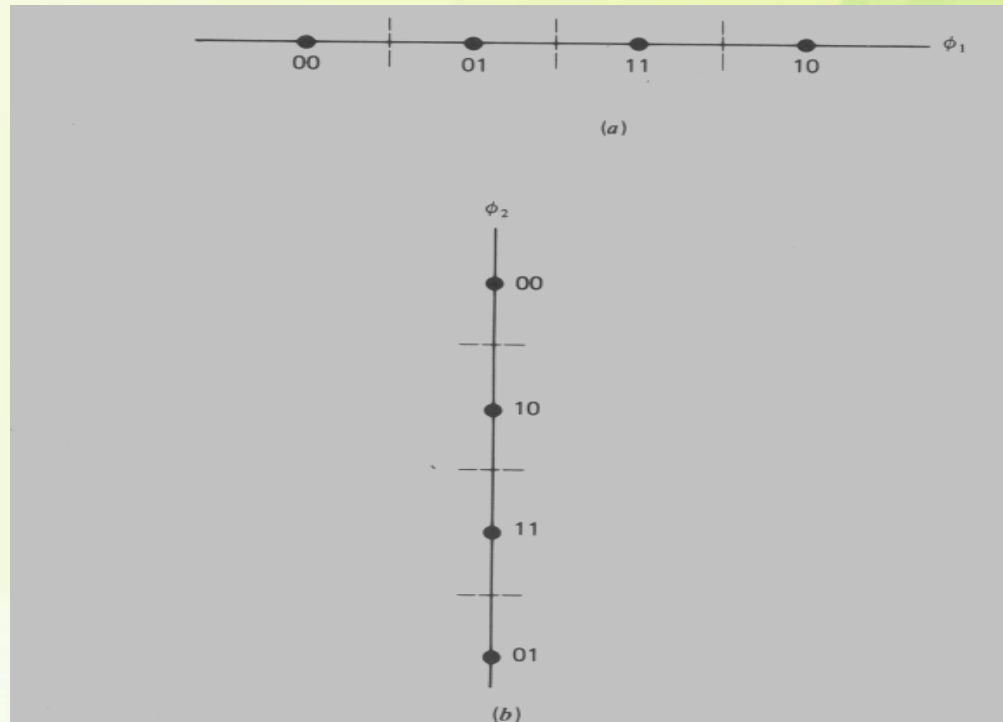


Fig: Decomposition of signal Constellation of M-ary QAM

The general form of an M-ary QAM signal can be defined as

$$S_i(t) = \sqrt{\frac{2E_{min}}{T_s}} a_i \cos(2\pi f_c t) + \sqrt{\frac{2E_{min}}{T_s}} b_i \sin(2\pi f_c t)$$
$$0 \leq t \leq T \quad i = 1, 2, \dots, M$$

where

E_{min} is the energy of the signal with the lowest amplitude and

a_i and b_i are a pair of independent integers chosen according to the location of the particular signal point.

- ⑩ In M-ary QAM energy per symbol and also distance between possible symbol states is not a constant.

Queries?

