

#### S J P N Trust's

#### Hirasugar Institute of Technology, Nidasoshi.

PCS IV Sem

**ECE Dept** 

Inculcating Values, Promoting Prosperity

2017-18

Approved by AICTE, Recognized by Govt. of Karnataka and Affiliated to VTU Belagavi

Department of Electronics & Communication Engg.

**Course: Principles of Communication Engg-15EC45.** Sem.: 4<sup>th</sup> (2017-18)

**Course Coordinator:** 

Dr. V. G. Kasabegoudar

#### **MODULE-1: Amplitude Modulation**

#### oIntroduction:

- Definition
- Why Modulation
- Types
- Applications
- OAmplitude Modulation:
  - Time & Frequency Domain description
  - Switching modulator
  - Envelop detector

#### Introduction

- Purpose of a communication system: convey information through a medium or communication channel.
- The information is often represented as a baseband signal, i.e. a signal whose spectrum extends from 0 to some maximum frequency.
- o Proper utilization of the communication channel often requires a shift of the range of baseband frequencies into other frequency ranges suitable for transmission, and a corresponding shift back to the original frequency range after reception.
- o A shift of the range of frequencies in a signal is accomplished by using modulation, which is defined as the process by which some characteristic of a carrier is varied in accordance with a modulating (signal)

#### **Introduction (Cont'd..)**

- A common form of the carrier is a sinusoidal wave, in which case we speak of continuous-wave modulation.
- The baseband signal is referred to as the modulating wave, and the result of the modulation process is referred to as the modulated wave.
- Modulation is performed at the transmitting end.
- At the receiving end, we require the original baseband signal to be restored.
- o This is accomplished by using a process known as demodulation, which is the reverse of the modulation process.

♦ A sinusoidal carrier wave:

 $A_c$  is the carrier amplitude  $f_c$  is the carrier frequency  $c(t) = A_c \cos(2\pi f_c t)$ Phase is assumed to be 0.

$$c(t) = A_c \cos(2\pi f_c t)$$

(3.1)

- *⋄ AM is defined as a process in which the amplitude of the carrier* wave c(t) is varied about a mean value, linearly with baseband signal m(t).
- ♦ AM wave, in its most general form

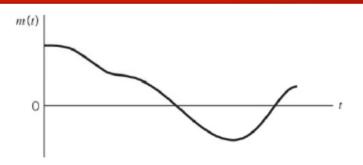
$$s(t) = A_c \left[ 1 + k_a m(t) \right] \cos(2\pi f_c t)$$
(3.2)

- $\diamond$  Typically, the carrier amplitude  $A_c$  and the message signal m(t) are measured in volts, in which case the  $k_a$  is measured in volt<sup>-1</sup>.
- $\diamond$   $k_a$ : amplitude sensitivity.[volt<sup>-1</sup>]
- m(t): modulating wave; the baseband signal that carries the message.
- $\diamond$  s(t): modulated wave.
- $\phi$  m(t) and  $A_c$  are measured in volts.

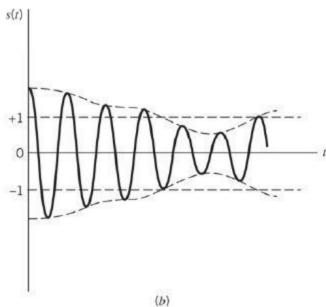
- $\diamond$  The <u>envelope</u> of s(t) has essentially the same shape as the baseband signal m(t) provided that two requirements are satisfied:
  - $\diamond$  1. The amplitude of  $k_a m(t)$  is always less than unity, that is,

$$|k_a m(t)| < 1 \text{ for all } t$$
 (3.3)

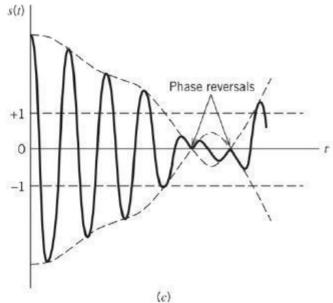
- ♦ It ensures that the function  $1 + k_a m(t)$  is always positive, and since an envelope is a positive function, we may express the envelope of the AM wave s(t) of Eq. (3.2) as  $A_c[1 + k_a m(t)]$ .
- ♦ When  $|k_a m(t)| > 1$  for any  $t \to the$  carrier wave becomes <u>overmodulated</u>, resulting in <u>carrier phase reversals</u> whenever the factor  $1 + k_a m(t)$  crosses zero. (<u>envelope distortion</u>)
- ♦ The absolute maximum value of  $k_a m(t)$  multiplied by 100 is referred to as the *percentage modulation*.



Baseband signal m(t)



AM wave for  $|k_a m(t)| \le 1$  for all t



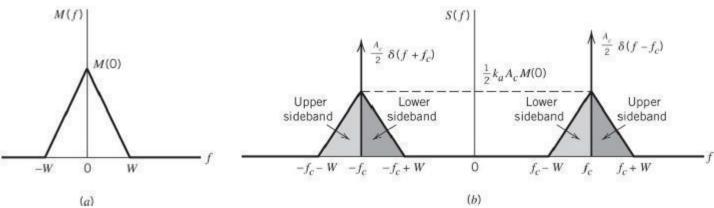
AM wave for  $|k_a m(t)| > 1$  for some t *Envelope distortion* 

 $\diamond$  2. The carrier frequency  $f_c$  is much greater than the highest frequency component W of the message signal m(t), that is

$$f_c \gg W \tag{3.4}$$

- ♦ We call W the <u>message bandwidth</u>. If the condition of Eq. (3.4) is not satisfied, an envelope can not be visualized satisfactorily.
- From Eq. (3.2), we find that the Fourier transform of the AM wave s(t) is given by  $s(t) = A_c \left[ 1 + k_a m(t) \right] \cos(2\pi f_c t)$  (3.2)  $\cos(2\pi f_c t) \rightleftharpoons \frac{1}{2} \left[ \delta(f f_c) + \delta(f + f_c) \right]$

$$S(f) = \frac{A_c}{2} \left[ \delta(f - f_c) + \delta(f + f_c) \right] + \frac{k_a A_c}{2} \left[ M(f - f_c) + M(f + f_c) \right]$$
(3.5)



- $\diamond$  From the spectrum of S(f), we note the following:
  - 1. As a result of the modulation process, the spectrum of the message signal m(t) for negative frequencies extending from -W to 0 becomes completely visible for positive frequencies, provided that the carrier frequency satisfies the condition  $f_c > W$ .
  - ♦ 2. For positive frequencies: The spectrum of an AM wave above  $f_c$  is referred to as the <u>upper sideband</u>, below  $f_c$  is referred to as the <u>lower sideband</u>. For negative frequencies: The <u>upper sideband</u> is below −  $f_c$  and the <u>lower sideband</u> is above −  $f_c$ . The condition  $f_c > W$  ensures that the sidebands do not overlap.
  - 3. For positive frequencies, the highest frequency component of the AM wave equals  $f_c + W$ , and the lowest frequency component equals  $f_c W$ . The difference between these two frequencies defines the <u>transmission bandwidth</u>  $B_T$  for an AM wave.

$$B_T = 2W \tag{3.6}$$





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Course: Principles of Communication Engg-15EC45. Sem.: 4<sup>th</sup> (2017-18)

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#### **MODULE-1: Amplitude Modulation**

- oIntroduction:
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- OAmplitude Modulation:
  - Time & Frequency Domain description
  - Switching modulator
  - Envelop detector

- ♦ Example 3.1 Single-Tone Modulation (1/3)
  - $\diamond$  Consider a modulating wave:  $m(t) = A_m \cos(2\pi f_m t)$ 
    - $s(t) = A_c \cos(2\pi f_c t)$   $s(t) = A_c \left[1 + \mu \cos(2\pi f_m t)\right] \cos(2\pi f_c t)$   $where \qquad \mu = k_a A_m \longrightarrow \mu \text{ :modulation factor}$ (3.7)

(or percentage modulation)

- ♦ To avoid overmodulation →  $|\mu|$ <1
- $\diamond$  Envelope of s(t):  $A_c[1 + \mu\cos(2\pi f_m t)]$

$$\frac{A_{\text{max}}}{A_{\text{min}}} = \frac{A_c \left(1 + \mu\right)}{A_c \left(1 - \mu\right)} \implies \mu = \frac{A_{\text{max}} - A_{\text{min}}}{A_{\text{max}} + A_{\text{min}}}$$

 $\diamond$   $A_{\max}$  and  $A_{\min}$  denote the maximum and minimum values of the envelope of the modulated wave.

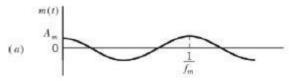
- Example 3.1 Single-Tone Modulation (2/3)
  - $\diamond$  Eq. (3.7) can be represented in this form:  $\cos A \cos B = \frac{1}{2} \{\cos(A-B) + \cos(A+B)\}$

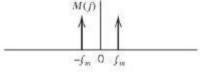
$$F(s(t) = A_{c}\cos(2\pi f_{c}t) + \frac{1}{2}\mu A_{c}\cos[2\pi (f_{c} + f_{m})t] + \frac{1}{2}\mu A_{c}\cos[2\pi (f_{c} - f_{m})t]$$

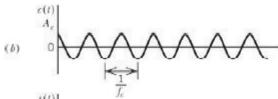
$$S(f) = \frac{1}{2}A_{c}[\delta(f - f_{c}) + \delta(f + f_{c})] + \frac{1}{4}\mu A_{c}[\delta(f - f_{c} - f_{m}) + \delta(f + f_{c} + f_{m})]$$

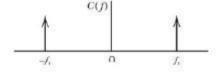
$$= \frac{1}{2}A_c \left[\delta(f - f_c) + \delta(f + f_c)\right] + \frac{1}{4}\mu A_c \left[\delta(f - f_c - f_m) + \delta(f + f_c + f_m)\right]$$

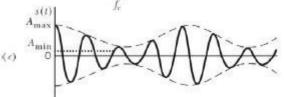
$$+\frac{1}{4}\mu A_{c}\Big[\delta\big(f-f_{c}+f_{m}\big)+\delta\big(f+f_{c}-f_{m}\big)\Big]$$

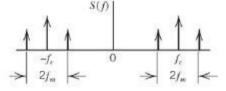




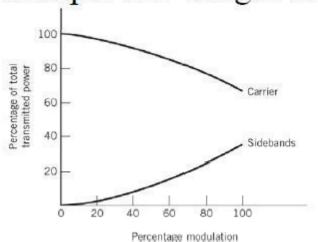








♦ Example 3.1 Single-Tone Modulation (3/3)



Carrier power = 
$$\frac{1}{2}A_c^2$$

Upper side-frequency power=
$$\frac{1}{8}\mu^2 A_c^2$$

Lower side-frequency power=
$$\frac{1}{8}\mu^2 A_c^2$$

In any case, the ratio of the total sideband power to the total power in the modulated wave is equal to

$$\mu^2/(2+\mu^2)$$

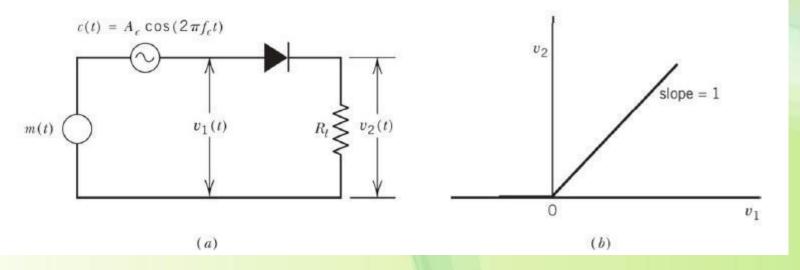
- $\diamond$  Depend only on the modulation factor  $\mu$ .
- If μ=1, the total power in the two side frequencies of the resulting AM
   wave is only one-third of the total power in the modulated wave.
- When the percentage modulation is less than 20 percent, the power in one side frequency is less than 1 percent of the total power in the AM wave.

- Switching Modulator (1/4)
  - ♦ One way to generate an AM wave: <u>Switching Modulator</u>.
    - Assume carrier wave c(t) is large in amplitude and the diode acts as an *ideal switch*.

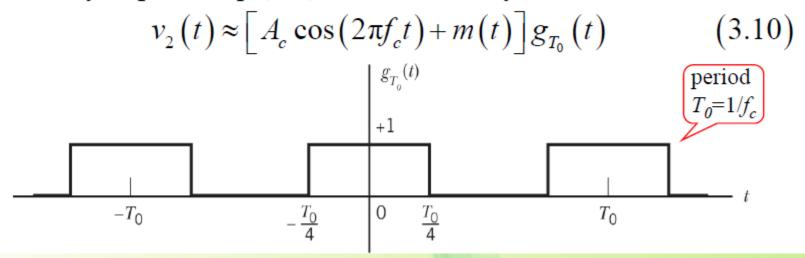
$$v_1(t) = A_c \cos(2\pi f_c t) + m(t) \tag{3.8}$$

$$v_2(t) \approx \begin{cases} v_1(t), & c(t) > 0 \\ 0, & c(t) < 0 \end{cases}$$

$$(3.9)$$



- Switching Modulator (2/4)
  - From Eq. (3.9), load voltage  $v_2(t)$  varies periodically between the values  $v_1(t)$  and zeros at a rate equal to the carrier frequency  $f_c$ .
  - By assuming a modulating wave that is weak compared with the carrier wave, we have effectively replace the nonlinear behavior of the diode by an approximately equivalent piecewise-linear time-varying operation.
  - ♦ We may express Eq. (3.9) mathematically as



♦ Switching Modulator (4/4)

$$g_{T_0}(t) = \frac{1}{2} + \frac{2}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{2n-1} \cos\left[2\pi f_c t (2n-1)\right]$$
(3.11)

- $\diamond$  Substituting Eq. (3.11) in (3.10),  $v_2(t)$  consists of two component
  - A desired AM wave:

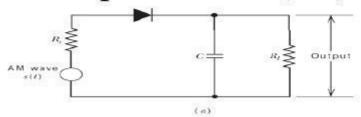
$$v_2(t) \approx [A_c \cos(2\pi f_c t) + m(t)] g_{T_0}(t)$$
 (3.10)

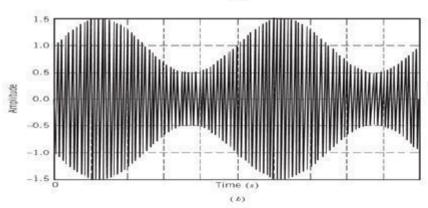
$$\frac{A_c}{2} \left[ 1 + \frac{4}{\pi A_c} m(t) \right] \cos(2\pi f_c t) , \quad k_a = \frac{4}{\pi A_c}$$

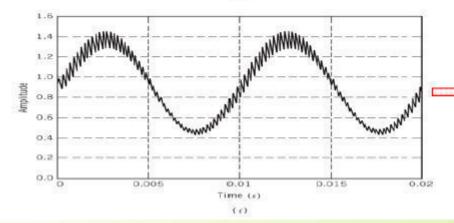
- Unwanted component, the spectrum of which contains
  - ♦ Delta function at 0,  $\pm 2f_c$ ,  $\pm 4f_c$  and so on.
  - Occupy frequency intervals of width 2W centered at  $0, \pm 3f_c, \pm 5f_c$  and so on, where W is the message bandwidth.
  - Be removed by using a band-pass filter with mid-band frequency  $f_c$  and bandwidth 2W, provide that  $f_c > 2W$ .

- ♦ Envelope Detector (1/2)
  - The process of <u>demodulation</u> is used to recover the original modulating wave from the incoming modulated wave.
  - ♦ One way to demodulate an AM wave: *envelope detector*.
    - Consist of a diode and a resistor-capacitor (RC) filter. (see next page)
  - ♦ The operation of envelope detector:
    - On a positive half-cycle of the input signal, the diode is forward-biased and the capacitor C charges up rapidly to the peak value of the input signal.
    - When the input signal falls below this value, the diode becomes reverse-biased and the capacitor C discharges slowly through the load resistor  $R_l$ . The discharging process continues until the next positive half-cycle.
    - When the input signal becomes greater than the voltage across the capacitor, the diode conducts again and the process is repeated.

### ♦ Envelope Detector (2/2)



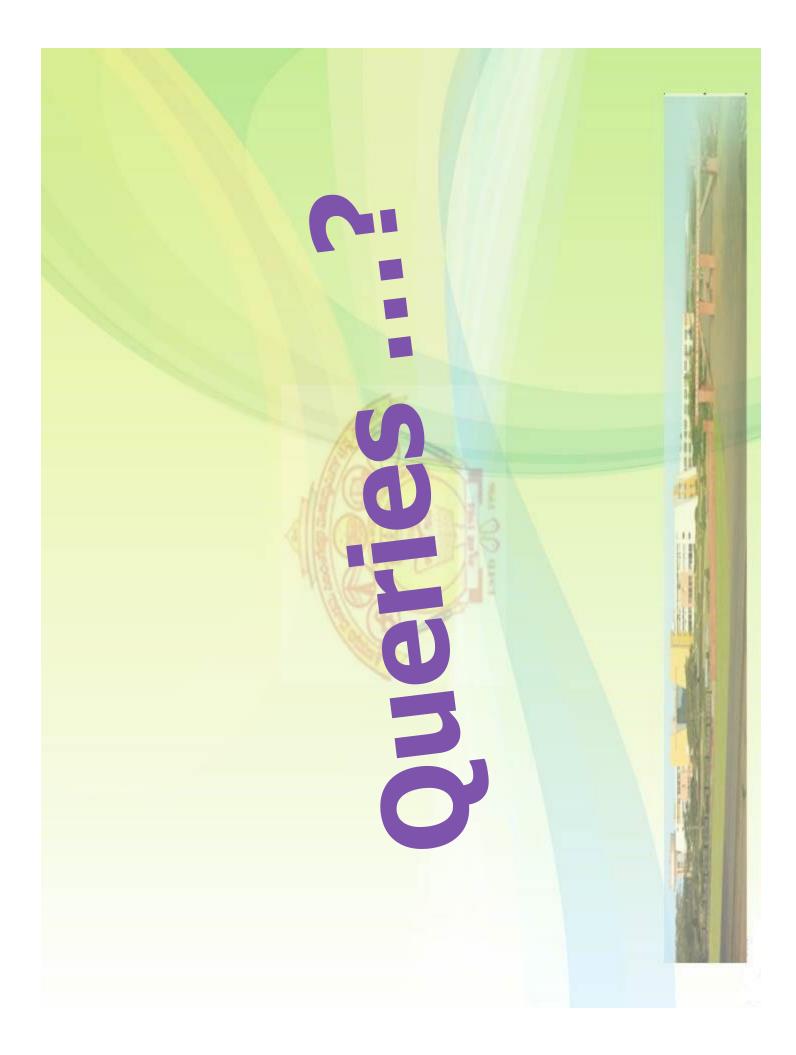




Envelope detector circuit diagram, assuming the diode is ideal, having a constant resistance  $r_f$  when forward biased and infinite resistance when reverse-biased.

→ A sinusoidal AM wave with 50 percent modulation.

Envelope detector output contains a small amount of ripple at the carrier frequency; this ripple is easily removed by the low-pass filter.





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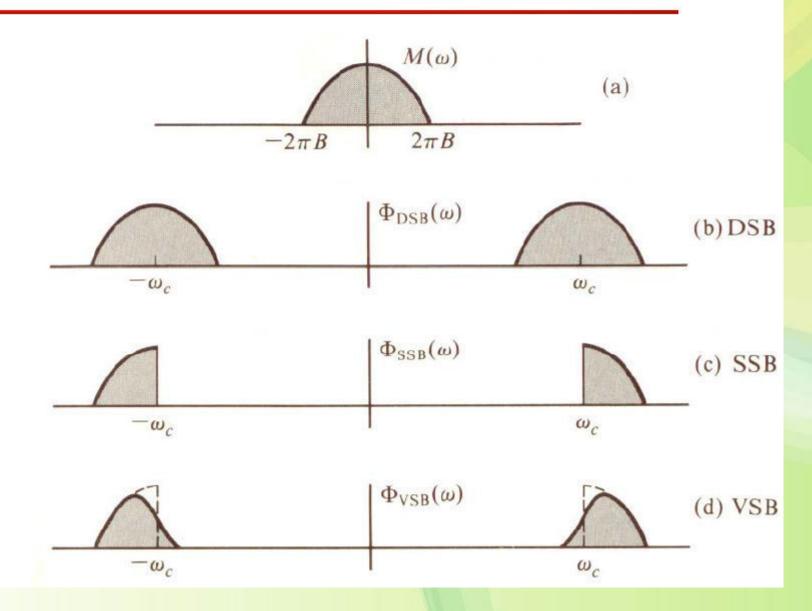
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#### TYPES OF AMPLITUDE MODULATION

- Three modified forms of amplitude modulation:
  - Double sideband-suppressed carrier (DSB-SC) modulation, in which the transmitted wave consists of only the upper and lower sidebands.
    - Transmitted power is saved through the suppression of the carrier. The channel bandwidth requirement is 2W.
  - Vestigial sideband (VSB) modulation, in which one sideband is passed almost completely and just a trace, or vestige, of the other sideband is retained.
    - The required channel bandwidth is in excess of the message bandwidth by an amount equal to the width of the vestigial sideband.
    - Suited for the transmission of wideband signals such as television signals.
  - Single sideband (SSB) modulation, in which the modulated wave consists only
    of the upper sideband or the lower sideband.
    - Suited for the transmission of voice signals by virtue of the energy gap that exists in the spectrum of voice signals between zero and a few hundred hertz.
    - The minimum transmitted power and minimum channel bandwidth: its principal disadvantage is increased cost and complexity.

### Spectra of the various modulated signals



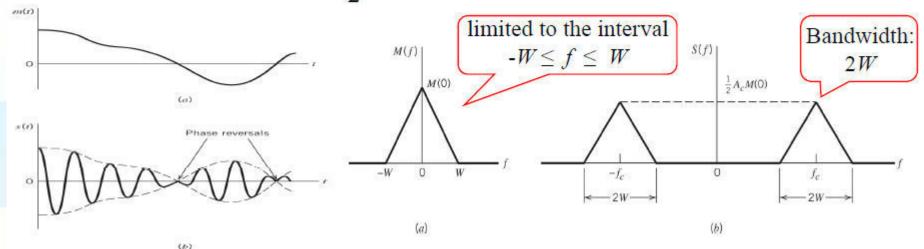
- Double sideband-suppressed carrier (DSB-SC) modulation.
  - $\diamond$  Product of the message signal m(t) and the carrier wave c(t):

$$s(t) = c(t)m(t) = A_c \cos(2\pi f_c t)m(t)$$
 (3.14)

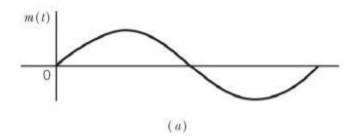
The modulated signal s(t) undergoes a *phase reversal* whenever the message signal m(t) crosses zero.

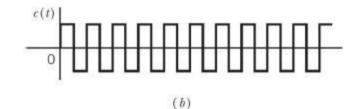
The envelope of a DSB-SC modulated signal is different from the message signal.

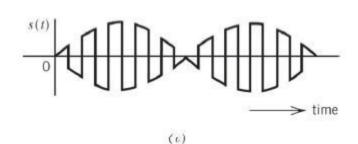
$$S(f) = \frac{1}{2} A_c \left[ M(f - f_c) + M(f + f_c) \right]$$
 (3.15)

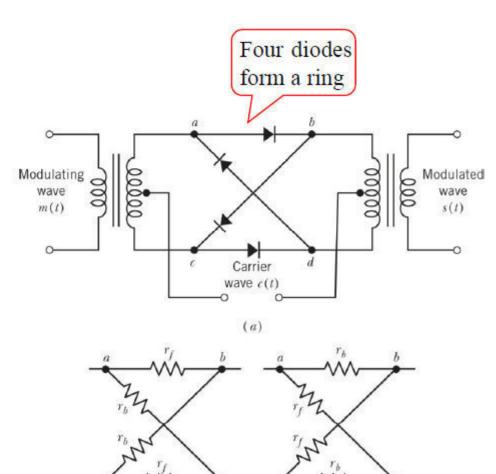


### ♦ Ring Modulator (1/4)









(b)

Source: WITS LAB

(c)

### ♦ Ring Modulator (2/4)

- Ring modulator is one of the most useful product modulator, well suited for generating a DSB-SC wave.
  - The diodes are controlled by a square-wave carrier c(t) of frequency  $f_c$ , which is applied longitudinally by means of two center-tapped transformers.
  - If the transformers are perfectly balanced and the diodes are identical, there is *no* leakage of the modulation frequency into the modulation output.
- ♦ The operation of the circuit.
  - Assuming that the diodes have a constant forward resistance  $r_f$  when switched on and a constant backward resistance  $r_b$  when switched off. And they switch as the carrier wave c(t) goes through zero.
  - On one half-cycle of the carrier wave, the outer diodes are switched to their forward resistance r<sub>f</sub> and the inner diodes are switched to their backward resistance r<sub>b</sub>. On the other half-cycle of the carrier wave, the diodes operate in the opposite condition.

- ♦ Ring Modulator (3/4)
  - The output voltage has the same magnitude as the output voltage, but they have opposite polarity.
  - In fact, the ring modulator acts as a commutator.
  - $\diamond$  Square-wave carrier c(t) can be represented by a Fourier series:

$$c(t) = \frac{4}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{2n-1} \cos\left[2\pi f_c t (2n-1)\right]$$
 (3.16)

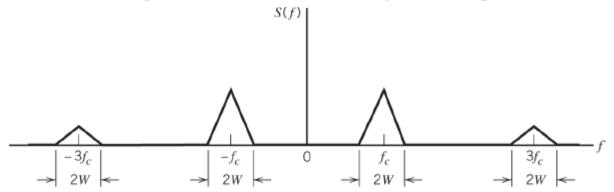
The ring modulator output is therefore

$$s(t) = c(t)m(t) = \frac{4}{\pi} \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{2n-1} \cos\left[2\pi f_c t(2n-1)\right] m(t)$$
 (3.17)

It is sometimes referred to as a <u>double-balanced modulator</u>, because it is balanced with respect to both the baseband signal and the square-wave carrier.

### ♦ Ring Modulator (4/4)

- ♦ Assuming that m(t) is limited to the frequency band  $-W \le f \le W$ , the spectrum of the modulator output consists of sidebands around each of the odd harmonics of the square-wave carrier m(t).
- ♦ To prevent sideband overlap  $\rightarrow f_c > W$ .
- $\diamond$  We can use a band-pass filter of mid-band frequency  $f_c$  and bandwidth 2W to select the desired pair of sidebands around the carrier frequency  $f_c$ .
  - The circuitry needed for the generation of a DSB-SC modulated wave consists of a ring modulator followed by a band-pass filter.







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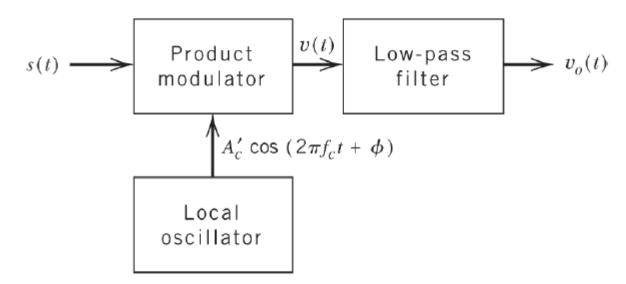
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♦ Coherent Detection (1/4)



♦ It is assumed that the local oscillator signal is exactly coherent or synchronized, in both *frequency and phase*, with carrier wave c(t) used in the product modulator to generate s(t). This method of demodulation is known as <u>coherent detection</u> or <u>synchronous</u> <u>demodulation</u>.

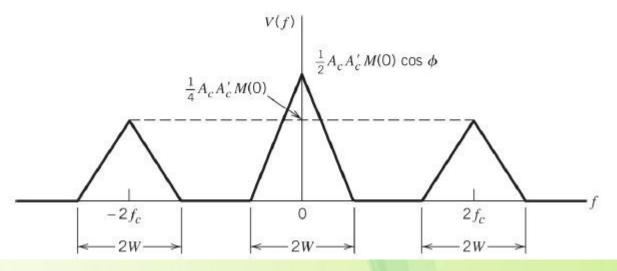
#### Coherent Detection (2/4)

For a more general demodulation process, we assume  $\phi$  is a arbitrary phase difference.

$$\upsilon(t) = A'_{c} \cos(2\pi f_{c}t + \phi)s(t)$$

$$= A_{c}A'_{c} \cos(2\pi f_{c}t)\cos(2\pi f_{c}t + \phi)m(t)$$

$$= \frac{1}{2}A_{c}A'_{c}\cos(4\pi f_{c}t + \phi)m(t) + \frac{1}{2}A_{c}A'_{c}\cos\phi m(t)$$
(3.18)



- ♦ Coherent Detection (3/4)
  - The first term in Eq.(3.18) is removed by low-pass filter, provided that the cut-off frequency of this filter is greater than W but less than  $2f_c W$ . This is satisfied by choosing  $f_c > W$ . Therefore:

 $\upsilon_o(t) = \frac{1}{2} A_c A_c' \cos \phi m(t) \tag{3.19}$ 

•  $v_o(t)$  is proportional to m(t) when the phase error  $\phi$  is a constant. Attenuated by a factor equal to  $\cos \phi$ .

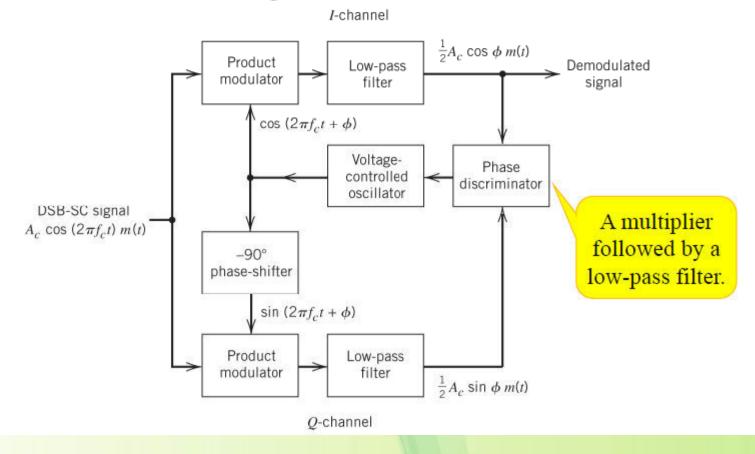
$$\begin{cases} v_{o\_{max}} = \frac{1}{2} A_c A_c' m(t), \text{ when } \phi = 0 \\ v_{o\_{mim}} = 0, & \text{when } \phi = \pm \frac{\pi}{2} \end{cases}$$
 (quadrature null effect)

• When the phase error  $\phi$  is constant, the detector provides an undistorted version of the original baseband signal m(t).

#### ♦ Coherent Detection (4/4)

- In practice, we usually find that the phase error  $\varphi$  varies randomly with time, due to random variations in communication channel. The result is that at the detector output, the multiplying factor  $\cos \varphi$  also varies randomly with time, which is obviously undesired.
- Provision must be made in the system to maintain the local oscillator in the receiver in <u>perfect synchronism</u>, in both frequency and phase, with the carrier wave used to generate the DSB-SC modulated signal in the transmitter.
- The resulting system complexity is the price that must be paid for suppressing the carrier wave to save transmitter power.

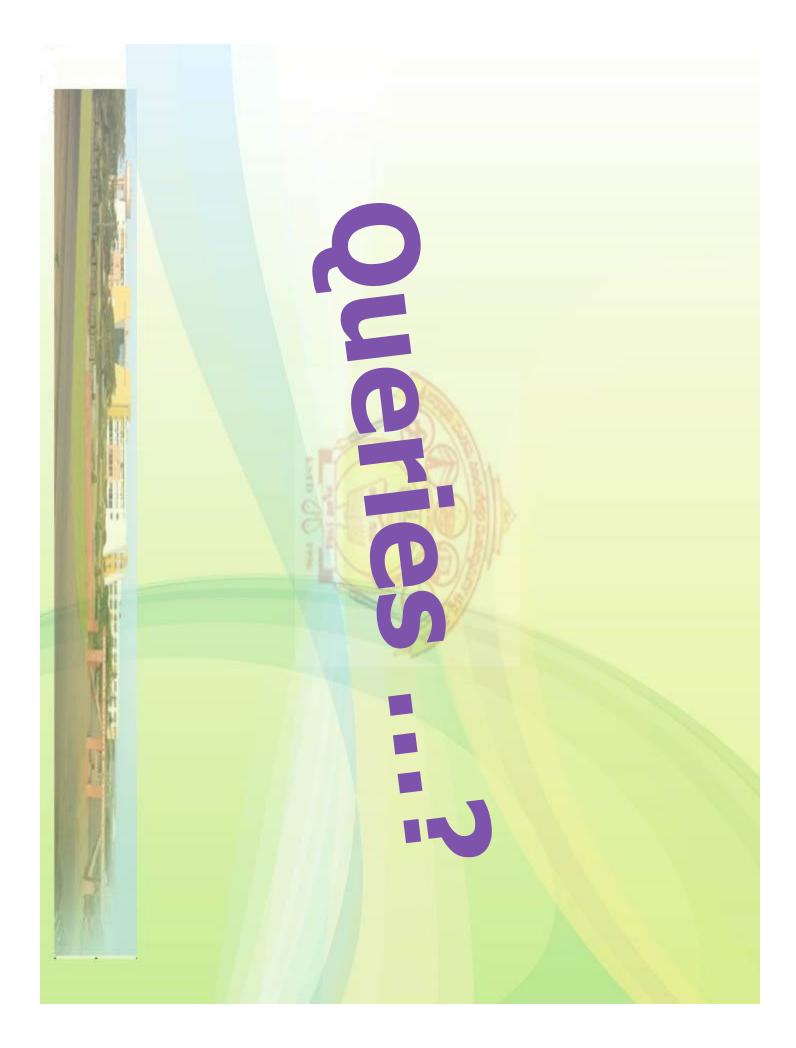
- ♦ Costas Receiver (1/2)
  - One method of obtaining a practical synchronous receiver system, suitable for demodulating DSB-SC waves.



- ♦ Costas Receiver (2/2)
  - $\diamond$  The frequency of the local oscillator is adjusted to be the same as the carrier frequency  $f_c$ , which is assumed known *a prior*.
  - ♦ In the upper path is referred to as the <u>in-phase coherent detector</u> or <u>I-channel</u>, and that in the lower path is referred to as the <u>quadrature-phase coherent detector</u> or <u>Q-channel</u>. These two detectors are coupled together to from a negative feedback system designed in such a way as to maintain the local oscillator synchronous with the carrier wave.
  - By combining the *I* and *Q*-channel outputs in <u>phase</u> <u>discriminator</u> (which consists of a <u>multiplier</u> followed by a <u>low-pass filter</u>), a dc control signal is obtained that automatically corrects for local phase errors in the <u>voltage-controlled oscillator</u> (VCO).

- Outputs of Product Modulator
  - $\bullet \quad \text{I-Channel} \quad A_c \cos(2\pi f_c t) m(t) \cos(2\pi f_c t + \phi) = \frac{1}{2} A_c m(t) \left\{ \cos(4\pi f_c t + \phi) + \cos\phi \right\}$
- Outputs of Low-Pass Filter
  - $\diamond \text{ I-Channel } \frac{1}{2} A_c m(t) \cos \phi$
  - $\diamond$  Q-Channel  $\frac{1}{2}A_c m(t)\sin\phi$
- Output of Multiplier

$$\left\{\frac{1}{2}A_{c}m(t)\cos\phi\right\}\cdot\left\{\frac{1}{2}A_{c}m(t)\sin\phi\right\} = \frac{1}{8}A_{c}^{2}\left[m(t)\right]^{2}\sin2\phi$$





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2017-18

**ECE Dept** 

### Department of Electronics & Communication Engg.

Course: Principles of Communication Engg-15EC45. Sem.: 4<sup>th</sup> (2017-18)

**Course Coordinator:** 

Dr. V. G. Kasabegoudar

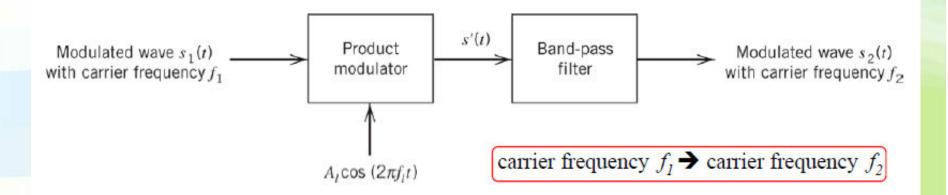
#### **MODULE-1: Amplitude Modulation**

Frequency Translation

Exercise Problems and Solutions

### Frequency Translation

- The basic operation involved in single-sideband modulation is in fact a form of *frequency translation*.
  - SSB modulation is sometimes referred to as <u>frequency changing</u>, <u>mixing</u>, or <u>heterodyning</u>.
- The <u>mixer</u> consists a product modulator followed by a band-pass filter.
  - Band-pass filter bandwidth: equal to that of the modulated signal s<sub>1</sub>(t) used as input.



### Frequency Translation

Due to frequency translation performed by the *mixer*: We may set

$$\begin{cases} f_2 = f_1 + f_l \\ f_l = f_2 - f_1 \end{cases}$$
 assume  $f_2 > f_l$  translated upward

or 
$$\begin{cases} f_2 = f_1 - f_1 \\ f_1 = f_1 - f_2 \end{cases}$$
 assume  $f_1 > f_2$  translated downward

$$s_1(t) \times A_l \cos(2\pi f_l t) = m(t) \cos(2\pi f_l t) \times A_l \cos(2\pi f_l t)$$

$$= \frac{1}{2} A_l m(t) \Big[ \cos(2\pi (f_1 + f_l)t) + \cos(2\pi (f_1 - f_l)t) \Big]$$

- The band-pass filter rejects the unwanted frequency and keeps the desired one.
- Mixing is a linear operation.



